

# Contents

<b>Abstract</b>	<b>vii</b>
<b>List of Figures</b>	<b>xiii</b>
<b>Nomenclature</b>	<b>xvii</b>
<b>1 Introduction</b>	<b>1</b>
1.1 Introduction to Networked Control Systems . . . . .	1
1.2 NCS architecture . . . . .	2
1.3 Literature Review . . . . .	5
1.3.1 State transmission vs Output transmission . . . . .	5
1.3.2 Scheduling algorithms . . . . .	9
1.3.3 NCSs with delays and dropouts . . . . .	15
1.3.4 Predictive control techniques . . . . .	17
1.4 Challenges in an NCS . . . . .	22
1.5 Motivation for the research . . . . .	23
1.6 Aim and Objectives of the thesis . . . . .	23
1.7 Contributions and Thesis outline . . . . .	24
<b>2 Predictive control of networked control system with event-triggering in two channels</b>	<b>27</b>
2.1 Introduction . . . . .	27
2.2 Preliminaries and problem formulation . . . . .	30
2.2.1 Event-triggering at feedback channel . . . . .	33
2.2.2 Observer . . . . .	34
2.2.3 State predictor . . . . .	35

2.2.4	State-feedback controller . . . . .	36
2.2.5	Event-triggering at forward channel . . . . .	36
2.2.6	Selector . . . . .	36
2.3	Predictive control scheme . . . . .	37
2.4	Controller and observer design . . . . .	39
2.5	Case studies . . . . .	41
2.5.1	Comparison with existing schemes . . . . .	49
2.6	Summary . . . . .	54

**3 Sequential output information based predictive control for networked control systems 55**

3.1	Introduction . . . . .	55
3.2	System description . . . . .	58
3.2.1	NCS overview . . . . .	58
3.2.2	Sequential observer . . . . .	62
3.2.3	Predictor and controller . . . . .	63
3.2.4	Event-triggering . . . . .	65
3.3	Overall system dynamics . . . . .	65
3.4	Controller and observer design . . . . .	67
3.5	Simulation results . . . . .	69
3.6	Summary . . . . .	74

**4 Predictive-triggered compensating control for networked control systems with random delays and dropouts 77**

4.1	Introduction . . . . .	77
4.2	System description . . . . .	78
4.2.1	Plant model . . . . .	80
4.2.2	State predictions . . . . .	80
4.2.3	Predictive-triggering at feedback channel . . . . .	82
4.2.4	Observer on the controller side . . . . .	83
4.2.5	Predictor and controller . . . . .	83
4.2.6	Predictive-triggering at the forward channel and the selector . . . . .	85
4.3	Predictive control scheme . . . . .	86

4.4	Controller and observer design . . . . .	88
4.5	Simulation results . . . . .	90
4.6	Summary . . . . .	97
<b>5</b>	<b>Conclusions and future scopes</b>	<b>99</b>
5.1	Conclusions . . . . .	99
5.2	Future scopes . . . . .	100
<b>A</b>	<b>Description of Simulation models</b>	<b>103</b>
A.1	Double-integrator model . . . . .	103
A.2	DC motor model . . . . .	104
A.3	Inverted pendulum model . . . . .	105

