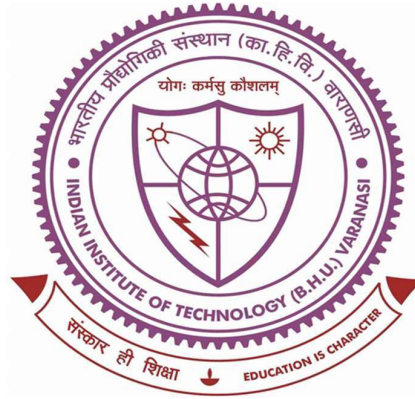


***WEARABLE SENSORS BASED GAIT ACQUISITION
FOR MOTION ANALYSIS AND PROSTHETIC
ANKLE-FOOT DESIGN***



**Thesis submitted in partial fulfilment
for the Award of Degree
*Doctor of Philosophy***

**by
*SACHIN NEGI***

***SCHOOL OF BIOMEDICAL ENGINEERING
INDIAN INSTITUTE OF TECHNOLOGY
(BANARAS HINDU UNIVERSITY)
VARANASI – 221005***

18021008

January 2022

APPENDIX A

GUI for Gait Analysis

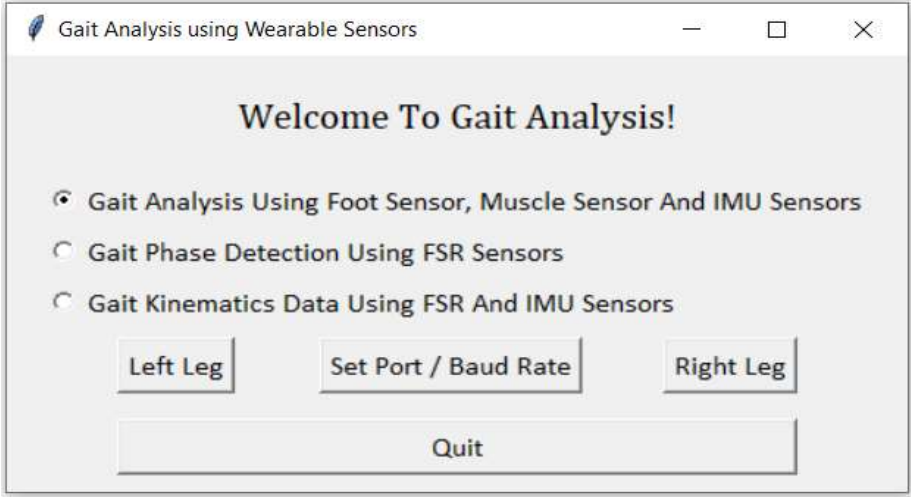


Figure A.1 Graphical user interface (GUI) for gait analysis using FSR, IMU, and EMG sensors

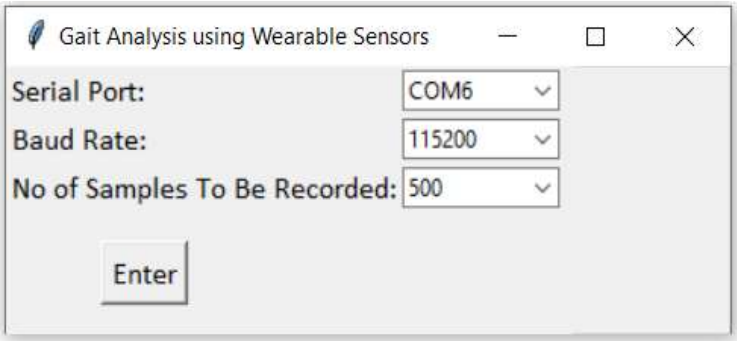


Figure A.2 GUI options for the selection of serial port, baud rate and number of samples to record

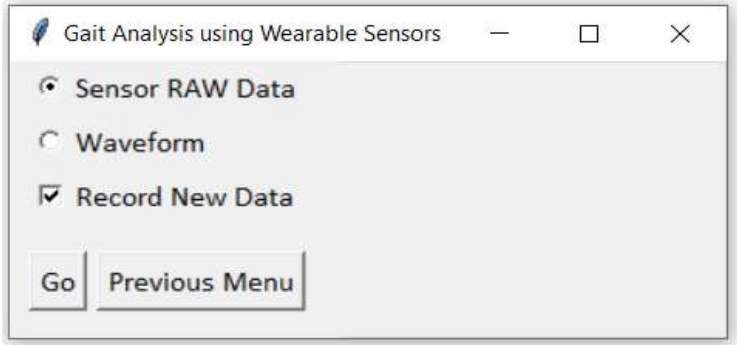


Figure A.3 GUI options to record new raw sensor data, and display the recorded waveform

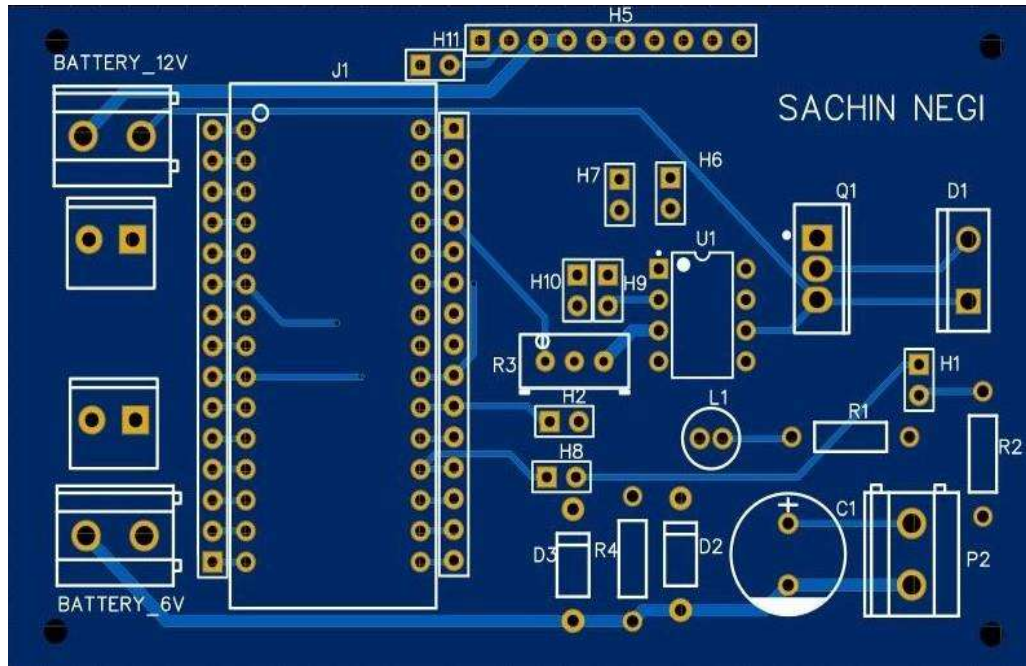


Figure B.3 Printed circuit board 2-D view for Arduino Nano-based MR damper control

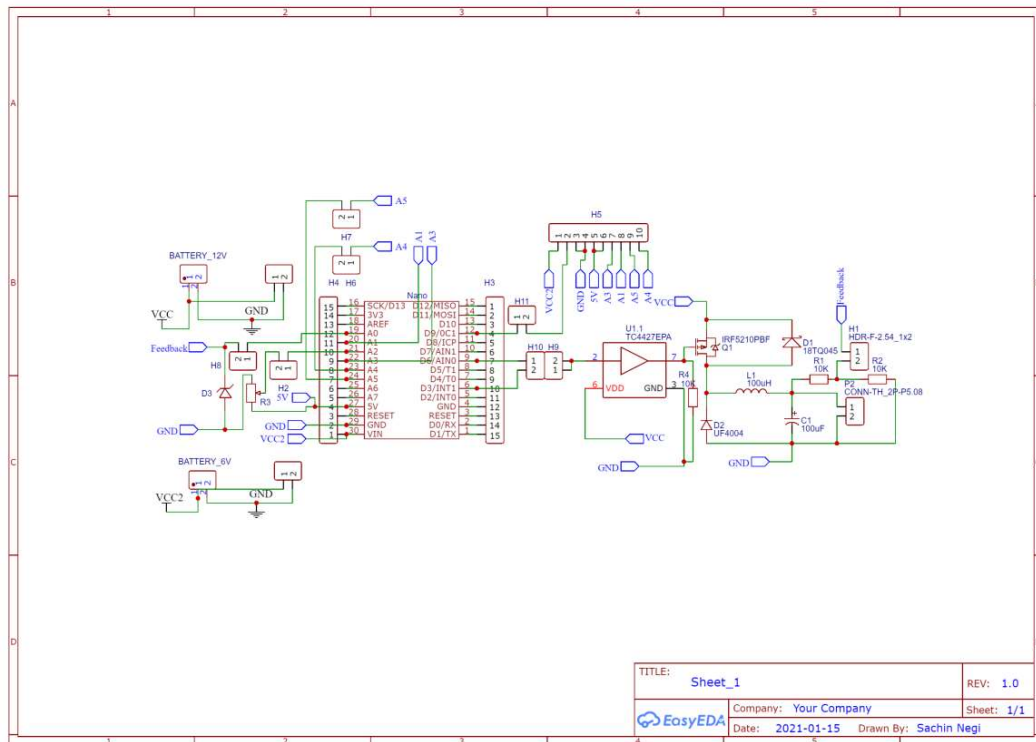


Figure B.4 Schematic diagram for Arduino Nano-based MR damper control circuit

APPENDIX C

Ethical Clearance Certificate

INSTITUTE OF MEDICAL SCIENCES
BANARAS HINDU UNIVERSITY

ECR/Bhu/Inst/UP/2014/Re-registration-2017 dt. 31.01.2017

No. Dean/2019/EC/ 1333 Dated: 07.05.2019


The Coordinator
School of Biomedical Engineering
Indian Institute of Technology
Banaras Hindu University

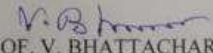
Dear Sir,

The Ethical Committee meeting was held on 07.05.2019 at 3.00 PM in the Chamber of the Dean, Faculty of Medicine, IMS to review the progress of the project 2016-17 as per the details given below::

Name of the Student	Sachin Negi
Synopsis Title	Study/Development of Ankle foot Protheses/Orthoses for Hilly region
Suggestions	The Head of Department of Radiodiagnosis should be consulted for the project and suggestion may be obtained.
Remarks	The Study is approved by the Institute Ethical Committee

This is for your information and necessary action at your end.


(DR. KIRAN GIRI)
MEMBER SECRETARY

Yours sincerely,

(PROF. V. BHATTACHARYA)
CHAIRPERSON OF THE ETHICAL COMMITTEE

APPENDIX D

Consent Statement of Amputee



NAUTIYAL ORTHOTIC-PROSTHETIC REHABILITATION CLINIC

BIO-Er. V.K. Nautiyal
P.O.E., M.O.P.S.I. (New Delhi)
Consultant:-
ORTHOTIST-PROSTHETIST & REHABILITATION



302 Haridwar Road, Shastri Nagar
Near Vidhan Sabha Chowk
Dehradun - 248001 (U.K.)
Phone : 9837224144, 7060079860
e-mail : vknautiyal@rediffmail.com
Web : www.norlimb.com

MEDI OTTOBOCK ALIMCO COLLEGE PARK
THE HIGH TECHNOLOGY ARTIFICIAL LIMBS

Ref. No.....

Dated..... 8/1/21

Consent Statement

I, Surjan Singh, age 32 years, height 168 cm, and weight 70 Kg, want to state that I have transtibial amputation for the last 11 years in an accident. And I have no objection to giving my trial to the Prosthetic leg model designed by Mr. Sachin Negi under the supervision of my prosthetist Dr. V. K. Nautiyal.

सुरजन सिंह

SURJAN SINGH

V.K. Nautiyal
NAUTIYAL
Orthotic-Prosthetic
Rehabilitation Clinic
Shastri Nagar, Haridwar Road,
Dehradun (U.K.)
Ph.: 9837224144, 7060079860

BIBLIOGRAPHY

- Abadi, M., Barham, P., Chen, J., Chen, Z., Davis, A., Dean, J., Devin, M., Ghemawat, S., Irving, G., Isard, M. and Kudlur, M., 2016. Tensorflow: A system for large-scale machine learning. In *12th {USENIX} symposium on operating systems design and implementation ({OSDI} 16)* (pp. 265-283).
- Adiputra, D., Nazmi, N., Bahiuddin, I., Ubaidillah, U., Imaduddin, F., Abdul Rahman, M.A., Mazlan, S.A. and Zamzuri, H., 2019, March. A review on the control of the mechanical properties of ankle foot orthosis for gait assistance. In *Actuators* (Vol. 8, No. 1, p. 10). Multidisciplinary Digital Publishing Institute.
- Al-Quraishi, M.S., Ishak, A.J., Ahmad, S.A., Hasan, M.K., Al-Qurishi, M., Ghapanchizadeh, H. and Alamri, A., 2017. Classification of ankle joint movements based on surface electromyography signals for rehabilitation robot applications. *Medical & biological engineering & computing*, 55(5), pp.747-758.
- Alimusaj, M., Fradet, L., Braatz, F., Gerner, H.J. and Wolf, S.I., 2009. Kinematics and kinetics with an adaptive ankle foot system during stair ambulation of transtibial amputees. *Gait & posture*, 30(3), pp.356-363.
- Allseits, E., Kim, K.J., Bennett, C., Gailey, R., Gaunaud, I. and Agrawal, V., 2018. A novel method for estimating knee angle using two leg-mounted gyroscopes for continuous monitoring with mobile health devices. *Sensors*, 18(9), p.2759.
- Aminian, Kamiar, et al. "Spatio-temporal parameters of gait measured by an ambulatory system using miniature gyroscopes." *Journal of biomechanics* 35.5 (2002): 689-699.
- Aminian, K. and Najafi, B., 2004. Capturing human motion using body-fixed sensors: outdoor measurement and clinical applications. *Computer animation and virtual worlds*, 15(2), pp.79-94.
- Anwary, A.R., Yu, H. and Vassallo, M., 2018. An automatic gait feature extraction method for identifying gait asymmetry using wearable sensors. *Sensors*, 18(2), p.676.
- Andersson, V., Dutra, R. and Araújo, R., 2014, March. Anthropometric and human gait identification using skeleton data from Kinect sensor. In *Proceedings of the 29th Annual ACM Symposium on Applied Computing* (pp. 60-61).
- Archer, C.M., Lach, J., Chen, S., Abel, M.F. and Bennett, B.C., 2014. Activity classification in users of ankle foot orthoses. *Gait & posture*, 39(1), pp.111-117.
- Arteaga, O., Escorza, J., Medina, I., Navas, R., Amores, K. and Morales, J.J., 2019. Prototype of Robotic Ankle-Foot Prosthesis with Active Damping Using Magnetorheological Fluids. *International Journal of Mechanical Engineering and Robotics Research*, 8(5).
- Au, S.K., Bonato, P. and Herr, H., 2005, June. An EMG-position controlled system for an active ankle-foot prosthesis: an initial experimental study. In *9th International Conference on Rehabilitation Robotics, 2005. ICORR 2005*. (pp. 375-379). IEEE.
- Au, S., Berniker, M. and Herr, H., 2008. Powered ankle-foot prosthesis to assist level-ground and stair-descent gaits. *Neural Networks*, 21(4), pp.654-666.
- Bamberg, S.J.M., Benbasat, A.Y., Scarborough, D.M., Krebs, D.E. and Paradiso, J.A., 2008. Gait analysis using a shoe-integrated wireless sensor system. *IEEE transactions on information technology in biomedicine*, 12(4), pp.413-423.
- Bae, J. and Tomizuka, M., 2013. A tele-monitoring system for gait rehabilitation with an inertial measurement unit and a shoe-type ground reaction force sensor. *Mechatronics*, 23(6), pp.646-651.

- Basu, J.K., Bhattacharyya, D. and Kim, T.H., 2010. Use of artificial neural network in pattern recognition. *International journal of software engineering and its applications*, 4(2).
- Bejarano, N.C., Ambrosini, E., Pedrocchi, A., Ferrigno, G., Monticone, M. and Ferrante, S., 2014. A novel adaptive, real-time algorithm to detect gait events from wearable sensors. *IEEE transactions on neural systems and rehabilitation engineering*, 23(3), pp.413-422.
- Bellman, R.D., Holgate, M.A. and Sugar, T.G., 2008, October. SPARKy 3: Design of an active robotic ankle prosthesis with two actuated degrees of freedom using regenerative kinetics. In *2008 2nd IEEE RAS & EMBS International Conference on Biomedical Robotics and Biomechanics* (pp. 511-516). IEEE.
- Benedetti, M.G., Agostini, V., Knaflitz, M. and Bonato, P., 2012. Muscle activation patterns during level walking and stair ambulation. *Applications of EMG in clinical and sports medicine*, 8(2), pp.117-130.
- Blaya, J.A. and Herr, H., 2004. Adaptive control of a variable-impedance ankle-foot orthosis to assist drop-foot gait. *IEEE Transactions on neural systems and rehabilitation engineering*, 12(1), pp.24-31.
- Bötzel, K., Marti, F.M., Rodríguez, M.Á.C., Plate, A. and Vicente, A.O., 2016. Gait recording with inertial sensors—How to determine initial and terminal contact. *Journal of biomechanics*, 49(3), pp.332-337.
- Cain, S.M., Gordon, K.E. and Ferris, D.P., 2007. Locomotor adaptation to a powered ankle-foot orthosis depends on control method. *Journal of neuroengineering and rehabilitation*, 4(1), pp.1-13.
- Caputo, J.M. and Collins, S.H., 2014. A universal ankle-foot prosthesis emulator for human locomotion experiments. *Journal of biomechanical engineering*, 136(3).
- Caruana, R. and Niculescu-Mizil, A., 2006, June. An empirical comparison of supervised learning algorithms. In *Proceedings of the 23rd international conference on Machine learning* (pp. 161-168).
- Census of India: Disabled Population, 2011, available at: https://censusindia.gov.in/census_and_you/disabled_population.aspx (accessed 15 July 2021).
- Chan, A.D. and Green, G.C., 2007. Myoelectric control development toolbox. *CMBES Proceedings*, 30.
- Chen, B., Zheng, E., Fan, X., Liang, T., Wang, Q., Wei, K. and Wang, L., 2013. Locomotion mode classification using a wearable capacitive sensing system. *IEEE transactions on neural systems and rehabilitation engineering*, 21(5), pp.744-755.
- Chen, B., Wang, Q. and Wang, L., 2014. Adaptive slope walking with a robotic transtibial prosthesis based on volitional EMG control. *IEEE/ASME Transactions on mechatronics*, 20(5), pp.2146-2157.
- Chen, W., Xu, Y., Wang, J. and Zhang, J., 2016. Kinematic analysis of human gait based on wearable sensor system for gait rehabilitation. *Journal of Medical and Biological Engineering*, 36(6), pp.843-856.
- Cherelle, P., Matthys, A., Grosu, V., Vanderborght, B. and Lefeber, D., 2012, June. The amp-foot 2.0: Mimicking intact ankle behavior with a powered transtibial prosthesis. In *2012 4th IEEE RAS & EMBS international conference on biomedical robotics and biomechanics (BioRob)* (pp. 544-549). IEEE.
- Cherelle, P., Grosu, V., Matthys, A., Vanderborght, B. and Lefeber, D., 2013. Design and validation of the ankle mimicking prosthetic (AMP-) foot 2.0. *IEEE Transactions on Neural Systems and Rehabilitation Engineering*, 22(1), pp.138-148.

- Cherelle, P., Grosu, V., Cestari, M., Vanderborght, B. and Lefeber, D., 2016. The AMP-Foot 3, new generation propulsive prosthetic feet with explosive motion characteristics: design and validation. *Biomedical engineering online*, 15(3), pp.21-36.
- Chu, K.H., Jiang, X. and Menon, C., 2017. Wearable step counting using a force myography-based ankle strap. *Journal of rehabilitation and assistive technologies engineering*, 4, p.2055668317746307.
- Collins, S.H. and Kuo, A.D., 2010. Recycling energy to restore impaired ankle function during human walking. *PLoS one*, 5(2), p.e9307.
- Connan, M., Ruiz Ramírez, E., Vodermayr, B. and Castellini, C., 2016. Assessment of a wearable force-and electromyography device and comparison of the related signals for myocontrol. *Frontiers in neurorobotics*, 10, p.17.
- Cortes, C. and Vapnik, V., 1995. Support-vector networks. *Machine learning*, 20(3), pp.273-297.
- Cover, T. and Hart, P., 1967. Nearest neighbor pattern classification. *IEEE transactions on information theory*, 13(1), pp.21-27.
- Cox, D.R., 1958. The regression analysis of binary sequences. *Journal of the Royal Statistical Society: Series B (Methodological)*, 20(2), pp.215-232.
- Culver, S., Bartlett, H., Shultz, A. and Goldfarb, M., 2018. A stair ascent and descent controller for a powered ankle prosthesis. *IEEE Transactions on Neural Systems and Rehabilitation Engineering*, 26(5), pp.993-1002.
- Day, S., 2002. Important factors in surface EMG measurement. *Bortec Biomedical Ltd publishers*, pp.1-17.
- De Luca, C.J., 2002. Surface electromyography: Detection and recording. *DelSys Incorporated*, 10(2), pp.1-10.
- De Luca, C., 2006. Electromyography. *Encyclopedia of medical devices and instrumentation*.
- Del Din, S., Godfrey, A., Galna, B., Lord, S. and Rochester, L., 2016. Free-living gait characteristics in ageing and Parkinson's disease: impact of environment and ambulatory bout length. *Journal of neuroengineering and rehabilitation*, 13(1), pp.1-12.
- Delva, M.L., Lajoie, K., Khoshnam, M. and Menon, C., 2020. Wrist-worn wearables based on force myography: on the significance of user anthropometry. *BioMedical Engineering OnLine*, 19(1), pp.1-18.
- Di Nardo, F., Ghetti, G. and Fioretti, S., 2013. Assessment of the activation modalities of gastrocnemius lateralis and tibialis anterior during gait: a statistical analysis. *Journal of Electromyography and Kinesiology*, 23(6), pp.1428-1433.
- Eilenberg, M.F., Geyer, H. and Herr, H., 2010. Control of a powered ankle-foot prosthesis based on a neuromuscular model. *IEEE transactions on neural systems and rehabilitation engineering*, 18(2), pp.164-173.
- Esposito, D., Gargiulo, G.D., Parajuli, N., Cesarelli, G., Andreozzi, E. and Bifulco, P., 2020, June. Measurement of muscle contraction timing for prosthesis control: a comparison between electromyography and force-myography. In *2020 IEEE International Symposium on Medical Measurements and Applications (MeMeA)* (pp. 1-6). IEEE.
- Ficanha, E.M. and Rastgaar, M., 2014a, August. Preliminary design and evaluation of a multi-axis ankle-foot prosthesis. In *5th IEEE RAS/EMBS International Conference on Biomedical Robotics and Biomechanics* (pp. 1033-1038). IEEE.
- Ficanha, E.M., Rastgaar, M. and Kaufman, K.R., 2014b. A two-axis cable-driven ankle-foot mechanism. *Robotics and Biomimetics*, 1(1), pp.1-13.

- Fisher, R.A., 1936. The use of multiple measurements in taxonomic problems. *Annals of eugenics*, 7(2), pp.179-188.
- Galván-Duque, C., Zavala-Yoé, R., Rodríguez-Reyes, G. and Mendoza-Cruz, F., 2015. Comparison between classical and intelligent identification systems for classification of gait events. *J. Control Science and Engineering*, 1, pp.21-34.
- Garreta, R. and Moncecchi, G., 2013. *Learning scikit-learn: machine learning in python*. Packt Publishing Ltd.
- Géron, A., 2019. *Hands-on machine learning with Scikit-Learn, Keras, and TensorFlow: Concepts, tools, and techniques to build intelligent systems*. O'Reilly Media.
- Godiyal, A.K., Verma, H.K., Khanna, N. and Joshi, D., 2018. A force myography-based system for gait event detection in overground and ramp walking. *IEEE Transactions on Instrumentation and Measurement*, 67(10), pp.2314-2323.
- Godiyal, A.K., Singh, U., Anand, S. and Joshi, D., 2019. Analysis of force myography based locomotion patterns. *Measurement*, 140, pp.497-503.
- Goršič, M., Kamnik, R., Ambrožič, L., Vitiello, N., Lefeber, D., Pasquini, G. and Munih, M., 2014. Online phase detection using wearable sensors for walking with a robotic prosthesis. *Sensors*, 14(2), pp.2776-2794.
- Gouwanda, D. and Gopalai, A.A., 2015. A robust real-time gait event detection using wireless gyroscope and its application on normal and altered gaits. *Medical engineering & physics*, 37(2), pp.219-225.
- Gouwanda, D., Gopalai, A.A. and Khoo, B.H., 2016. A low cost alternative to monitor human gait temporal parameters—wearable wireless gyroscope. *IEEE Sensors Journal*, 16(24), pp.9029-9035.
- Grimmer, M., Eslamy, M., Glied, S. and Seyfarth, A., 2012, May. A comparison of parallel- and series elastic elements in an actuator for mimicking human ankle joint in walking and running. In *2012 IEEE International Conference on Robotics and Automation* (pp. 2463-2470). IEEE.
- Gupta, R. and Agarwal, R., 2018. Continuous human locomotion identification for lower limb prosthesis control. *CSI Transactions on ICT*, 6(1), pp.17-31.
- Ha, K.H., Varol, H.A. and Goldfarb, M., 2010. Volitional control of a prosthetic knee using surface electromyography. *IEEE Transactions on Biomedical Engineering*, 58(1), pp.144-151.
- Hall, S.J. and Lysell, D., 1995. *Basic biomechanics*. St. Louis: Mosby.
- Hansen, A.H., Childress, D.S., Miff, S.C., Gard, S.A. and Mesplay, K.P., 2004. The human ankle during walking: implications for design of biomimetic ankle prostheses. *Journal of biomechanics*, 37(10), pp.1467-1474.
- He, H., Kiguchi, K. and Horikawa, E., 2007. A study on lower-limb muscle activities during daily lower-limb motions. *International journal of Bioelectromagnetism*, 9(2), pp.79-84.
- Hermens, H.J., Freriks, B., Disselhorst-Klug, C. and Rau, G., 2000. Development of recommendations for SEMG sensors and sensor placement procedures. *Journal of electromyography and Kinesiology*, 10(5), pp.361-374.
- Herr, H., 2009. Exoskeletons and orthoses: classification, design challenges and future directions. *Journal of neuroengineering and rehabilitation*, 6(1), pp.1-9.
- Herr, H.M. and Grabowski, A.M., 2012. Bionic ankle-foot prosthesis normalizes walking gait for persons with leg amputation. *Proceedings of the Royal Society B: Biological Sciences*, 279(1728), pp.457-464.

- Ho, T.K., 1995, August. Random decision forests. In *Proceedings of 3rd international conference on document analysis and recognition* (Vol. 1, pp. 278-282). IEEE.
- Hooda, N., Das, R. and Kumar, N., 2020. Fusion of EEG and EMG signals for classification of unilateral foot movements. *Biomedical Signal Processing and Control*, 60, p.101990.
- Howell, A.M., Kobayashi, T., Hayes, H.A., Foreman, K.B. and Bamberg, S.J.M., 2013. Kinetic gait analysis using a low-cost insole. *IEEE Transactions on Biomedical Engineering*, 60(12), pp.3284-3290.
- Huang, H., Kuiken, T.A. and Lipschutz, R.D., 2008. A strategy for identifying locomotion modes using surface electromyography. *IEEE Transactions on Biomedical Engineering*, 56(1), pp.65-73.
- Huang, H., Zhang, F., Hargrove, L.J., Dou, Z., Rogers, D.R. and Englehart, K.B., 2011. Continuous locomotion-mode identification for prosthetic legs based on neuromuscular-mechanical fusion. *IEEE Transactions on Biomedical Engineering*, 58(10), pp.2867-2875.
- Hunter, J.D., 2007. Matplotlib: A 2D graphics environment. *Computing in science & engineering*, 9(03), pp.90-95.
- Interlink Electronics FSR™ Force Sensing Resistors™, available at: http://www.trossenrobotics.com/productdocs/FSR_Integration_Guide.pdf (accessed 14 June 2021).
- Isezaki, T., Kadone, H., Nijima, A., Aoki, R., Watanabe, T., Kimura, T. and Suzuki, K., 2019. Sock-type wearable sensor for estimating lower leg muscle activity using distal EMG signals. *Sensors*, 19(8), p.1954.
- Ivanenko, Y.P., Poppele, R.E. and Lacquaniti, F., 2004. Five basic muscle activation patterns account for muscle activity during human locomotion. *The Journal of physiology*, 556(1), pp.267-282.
- Jamal, M.Z., 2012. Signal acquisition using surface EMG and circuit design considerations for robotic prosthesis. *Computational Intelligence in Electromyography Analysis-A Perspective on Current Applications and Future Challenges*, 18, pp.427-448.
- Jang, J.S., 1993. ANFIS: adaptive-network-based fuzzy inference system. *IEEE transactions on systems, man, and cybernetics*, 23(3), pp.665-685.
- Jiang, X., Chu, H.T., Xiao, Z.G., Merhi, L.K. and Menon, C., 2016, November. Ankle positions classification using force myography: An exploratory investigation. In *2016 IEEE Healthcare Innovation Point-Of-Care Technologies Conference (HI-POCT)* (pp. 29-32). IEEE.
- Jiang, X., Chu, K.H., Khoshnam, M. and Menon, C., 2018. A wearable gait phase detection system based on force myography techniques. *Sensors*, 18(4), p.1279.
- Jordan, M.I. and Mitchell, T.M., 2015. Machine learning: Trends, perspectives, and prospects. *Science*, 349(6245), pp.255-260.
- Joshi, D., Nakamura, B.H. and Hahn, M.E., 2014. A novel approach for toe off estimation during locomotion and transitions on ramps and level ground. *IEEE journal of biomedical and health informatics*, 20(1), pp.153-157.
- Joshi, D., Nakamura, B.H. and Hahn, M.E., 2015. High energy spectrogram with integrated prior knowledge for EMG-based locomotion classification. *Medical engineering & physics*, 37(5), pp.518-524.
- Jung, J.Y., Heo, W., Yang, H. and Park, H., 2015. A neural network-based gait phase classification method using sensors equipped on lower limb exoskeleton robots. *Sensors*, 15(11), pp.27738-27759.

- Kadhim, D.A., Raheema, M.N. and Hussein, J.S., 2020. Design of an Intelligent Controller for Above Knee Prostheses based on an Adaptive Neuro-Fuzzy Inference System. In *IOP Conference Series: Materials Science and Engineering* (Vol. 671, No. 1, p. 012066). IOP Publishing.
- Kannape, O.A. and Herr, H.M., 2014, August. Volitional control of ankle plantar flexion in a powered transtibial prosthesis during stair-ambulation. In *2014 36th Annual International Conference of the IEEE Engineering in Medicine and Biology Society* (pp. 1662-1665). IEEE.
- Kim, D.H., Cho, C.Y. and Ryu, J., 2014. Real-Time Locomotion Mode Recognition Employing Correlation Feature Analysis Using EMG Pattern. *Etri Journal*, 36(1), pp.99-105.
- Kim, M. and Lee, D., 2017. Development of an IMU-based foot-ground contact detection (FGCD) algorithm. *Ergonomics*, 60(3), pp.384-403.
- Khandelwal, S. and Wickström, N., 2016. Gait event detection in real-world environment for long-term applications: Incorporating domain knowledge into time-frequency analysis. *IEEE transactions on neural systems and rehabilitation engineering*, 24(12), pp.1363-1372.
- Kumar, P.K., Charan, M. and Kanagaraj, S., 2017. Trends and challenges in lower limb prosthesis. *IEEE Potentials*, 36(1), pp.19-23.
- Kurniawan, R., Ramadhan, F.I.P., Astuti, W., Rizaldi, F.Y., Aji, M.B., Syai'in, M., Indarti, R., Rinanto, N., Setiyoko, A.S., Jamiin, M.A. and Herijono, B., 2019, October. Electric Bionic Legs Used Gyroscope And Accelerometer With Fuzzy Method. In *2019 International Symposium on Electronics and Smart Devices (ISESD)* (pp. 1-5). IEEE.
- LaPrè, A.K. and Sup, F., 2011, August. Simulation of a slope adapting ankle prosthesis provided by semi-active damping. In *2011 Annual International Conference of the IEEE Engineering in Medicine and Biology Society* (pp. 587-590). IEEE.
- Latif, T., Ellahi, C.M., Choudhury, T.A. and Rabbani, K.S., 2008, December. Design of a cost-effective EMG driven bionic leg. In *2008 International Conference on Electrical and Computer Engineering* (pp. 80-85). IEEE.
- Lawson, B.E., Mitchell, J., Truex, D., Shultz, A., Ledoux, E. and Goldfarb, M., 2014. A robotic leg prosthesis: Design, control, and implementation. *IEEE Robotics & Automation Magazine*, 21(4), pp.70-81.
- Lee, J.K. and Park, E.J., 2011. Quasi real-time gait event detection using shank-attached gyroscopes. *Medical & biological engineering & computing*, 49(6), pp.707-712.
- Lemoine, R. and Mastroianni, T., 2019. Classification of software control architectures for a powered prosthesis through conventional gait analysis using machine learning applications. *Journal of Mechanics in Medicine and Biology*, 19(06), p.1950044.
- Li, Q., Wang, Y., Sharf, A., Cao, Y., Tu, C., Chen, B. and Yu, S., 2018. Classification of gait anomalies from kinect. *The Visual Computer*, 34(2), pp.229-241.
- Liu, M., Zhang, F. and Huang, H.H., 2017. An adaptive classification strategy for reliable locomotion mode recognition. *Sensors*, 17(9), p.2020.
- Malvade, P.S., Joshi, A.K. and Madhe, S.P., 2017, April. IoT based monitoring of foot pressure using FSR sensor. In *2017 International Conference on Communication and Signal Processing (ICCSP)* (pp. 0635-0639). IEEE.
- Mannini, A., Trojaniello, D., Cereatti, A. and Sabatini, A.M., 2016. A machine learning framework for gait classification using inertial sensors: Application to elderly, post-stroke and huntington's disease patients. *Sensors*, 16(1), p.134.

- Maqbool, H.F., Husman, M.A.B., Awad, M.I., Abouhossein, A., Iqbal, N. and Dehghani-Sanij, A.A., 2016. A real-time gait event detection for lower limb prosthesis control and evaluation. *IEEE transactions on neural systems and rehabilitation engineering*, 25(9), pp.1500-1509.
- Meléndez-Calderón, A., Caltenco-Arciniega, H.A., Dosen, S. and Chong-Quero, J.E., 2007, September. On-line simulation tool for the design and analysis of lower-limb prosthetic devices. In *2007 4th International Conference on Electrical and Electronics Engineering* (pp. 98-101). IEEE.
- Malesevic, J.M., Foot movement classification based on signals from accelerometer. In *2011 19th Telecommunications Forum (TELFOR) Proceedings of Papers*.
- Martinez, R.C., Avitia, R.L., Bravo, M.E. and Reyna, M.A., 2014, March. A low cost design of powered ankle-knee prosthesis for lower limb amputees. In *Proceedings of the International Joint Conference on Biomedical Engineering Systems and Technologies vol. 1. SCITEPRESS-Science and Technology Publications, Lda* (pp. 253-258).
- Massalin, Y., Abdrakhmanova, M. and Varol, H.A., 2017. User-independent intent recognition for lower limb prostheses using depth sensing. *IEEE Transactions on Biomedical Engineering*, 65(8), pp.1759-1770.
- Masum, H., Bhaumik, S. and Ray, R., 2014. Conceptual design of a powered ankle-foot prosthesis for walking with inversion and eversion. *Procedia Technology*, 14, pp.228-235.
- Menard, S., 2002. *Applied logistic regression analysis* (Vol. 106). Sage.
- Mitchell, M., Craig, K., Kyberd, P., Biden, E. and Bush, G., 2013. Design and development of ankle-foot prosthesis with delayed release of plantarflexion. *Journal of Rehabilitation Research & Development*, 50(3).
- Muller, P., Steel, T. and Schauer, T., 2015, March. Experimental evaluation of a novel inertial sensor based real-time gait phase detection algorithm. In *Proceedings of the Technically Assisted Rehabilitation Conference*.
- Muñoz, B., Castaño-Pino, Y.J., Paredes, J.D.A. and Navarro, A., 2018, September. Automated gait analysis using a Kinect camera and wavelets. In *2018 IEEE 20th International Conference on e-Health Networking, Applications and Services (Healthcom)* (pp. 1-5). IEEE.
- Muro-De-La-Herran, A., Garcia-Zapirain, B. and Mendez-Zorrilla, A., 2014. Gait analysis methods: An overview of wearable and non-wearable systems, highlighting clinical applications. *Sensors*, 14(2), pp.3362-3394.
- MyoWare Muscle Sensor (AT-04-001), available at: <http://www.advancertechnologies.com/p/myoware.html> (accessed 14 June 2021).
- Nandy, A., Mondal, S., Chakraborty, P. and Nandi, G.C., 2012, August. Development of a robust microcontroller based intelligent prosthetic limb. In *International Conference on Contemporary Computing* (pp. 452-462). Springer, Berlin, Heidelberg.
- Negi, S., Kumar, Y. and Mishra, V.M., 2016, September. Feature extraction and classification for EMG signals using linear discriminant analysis. In *2016 2nd International Conference on Advances in Computing, Communication, & Automation (ICACCA)(Fall)* (pp. 1-6). IEEE.
- Negi, S., Kumar, Y. and Mishra, V.M., 2017. MLPNN and kNN Based Classification of sEMG Signal for Myoelectric Control of Upper Limb Prosthesis. In *RICE* (pp. 269-272).
- Negi, S., Kumar, Y. and Mishra, V.M., 2018. Myoelectric control of upper limb prostheses using linear discriminant analysis and multilayer perceptron neural network with back propagation algorithm. *International Journal of Computational Systems Engineering*, 4(2-3), pp.120-126

- Negi, S., CBS Negi, P. and Sharma, S., 2020. Electromyographic and acceleration signals-based gait phase analysis for multiple terrain classification using deep learning. *International Journal of Advanced Research in Engineering and Technology*, 11(6).
- Negi, S., Negi, P.C., Sharma, S. and Sharma, N., 2020. Human locomotion classification for different terrains using machine learning techniques. *Critical Reviews™ in Biomedical Engineering*, 48(4).
- Negi, S., Sharma, S. and Sharma, N., 2021. FSR and IMU sensors-based human gait phase detection and its correlation with EMG signal for different terrain walk. *Sensor Review*.
- Ng, S.K. and Chizeck, H.J., 1994, November. Fuzzy vs. non-fuzzy rule base for gait event detection. In *Proceedings of 16th Annual International Conference of the IEEE Engineering in Medicine and Biology Society* (Vol. 2, pp. 1069-1070). IEEE.
- Nordin, N.D., Muthalif, A.G. and M Razali, M.K., 2018. Control of transtibial prosthetic limb with magnetorheological fluid damper by using a fuzzy PID controller. *Journal of Low Frequency Noise, Vibration and Active Control*, 37(4), pp.1067-1078.
- Opitz, D. and Maclin, R., 1999. Popular ensemble methods: An empirical study. *Journal of artificial intelligence research*, 11, pp.169-198.
- Oskoei, M.A. and Hu, H., 2007. Myoelectric control systems—A survey. *Biomedical signal processing and control*, 2(4), pp.275-294.
- Pandit, S., Godiyal, A.K., Vimal, A.K., Singh, U., Joshi, D. and Kalyanasundaram, D., 2018. An affordable insole-sensor-based trans-femoral prosthesis for normal gait. *Sensors*, 18(3), p.706.
- Pappas, I.P., Popovic, M.R., Keller, T., Dietz, V. and Morari, M., 2001. A reliable gait phase detection system. *IEEE Transactions on neural systems and rehabilitation engineering*, 9(2), pp.113-125.
- Pappas, I.P., Keller, T., Mangold, S., Popovic, M.R., Dietz, V. and Morari, M., 2004. A reliable gyroscope-based gait-phase detection sensor embedded in a shoe insole. *IEEE sensors journal*, 4(2), pp.268-274.
- Parsan, A. and Tosunoglu, S., 2012. A novel control algorithm for ankle-foot prosthesis. In *Florida conference on recent advances in robotics*, Boca Raton.
- Patla, A.E., 1985. Some characteristics of EMG patterns during locomotion: implications for the locomotor control process. *Journal of motor behavior*, 17(4), pp.443-461.
- Pedregosa, F., Varoquaux, G., Gramfort, A., Michel, V., Thirion, B., Grisel, O., Blondel, M., Prettenhofer, P., Weiss, R., Dubourg, V. and Vanderplas, J., 2011. Scikit-learn: Machine learning in Python. *the Journal of machine Learning research*, 12, pp.2825-2830.
- Perry, J. and Davids, J.R., 1992. Gait analysis: normal and pathological function. *Journal of Pediatric Orthopaedics*, 12(6), p.815.
- Phinyomark, A., Phukpattaranont, P. and Limsakul, C., 2012. Feature reduction and selection for EMG signal classification. *Expert systems with applications*, 39(8), pp.7420-7431.
- Pickle, N.T., Grabowski, A.M., Auyang, A.G. and Silverman, A.K., 2016. The functional roles of muscles during sloped walking. *Journal of biomechanics*, 49(14), pp.3244-3251.
- Prakash, A., Sharma, S. and Sharma, N., 2019. A compact-sized surface EMG sensor for myoelectric hand prosthesis. *Biomedical Engineering Letters*, 9(4), pp.467-479.
- Prakash, C., Gupta, K., Kumar, R. and Mittal, N., 2016. Fuzzy logic-based gait phase detection using passive markers. In *Proceedings of Fifth International Conference on Soft Computing for Problem Solving* (pp. 561-572). Springer, Singapore.

- Prakash, C., Kumar, R. and Mittal, N., 2018. Recent developments in human gait research: parameters, approaches, applications, machine learning techniques, datasets and challenges. *Artificial Intelligence Review*, 49(1), pp.1-40.
- Quinlan, J.R., 1986. Induction of decision trees. *Machine learning*, 1(1), pp.81-106.
- Raschka, S., 2015. *Python machine learning*. Packt publishing ltd.
- Rawal, B.R., Yadav, A. and Pare, V., 2016. Life estimation of knee joint prosthesis by combined effect of fatigue and wear. *Procedia Technology*, 23, pp.60-67.
- RHINO MOTION CONTROLS RMCS-220X High-Torque Encoder DC Servo Motor and Driver, available at: https://robokits.download/downloads/RMCS220x_DC Servo_Driver.pdf (accessed 14 June 2021).
- Riener, R., Rabuffetti, M. and Frigo, C., 2002. Stair ascent and descent at different inclinations. *Gait & posture*, 15(1), pp.32-44.
- Rietman, J.S., Postema, K. and Geertzen, J.H.B., 2002. Gait analysis in prosthetics: opinions, ideas and conclusions. *Prosthetics and orthotics international*, 26(1), pp.50-57.
- Rish, I., 2001, August. An empirical study of the naive Bayes classifier. In *IJCAI 2001 workshop on empirical methods in artificial intelligence* (Vol. 3, No. 22, pp. 41-46).
- Rocha, A.P., Choupina, H.M.P., Vilas-Boas, M.D.C., Fernandes, J.M. and Cunha, J.P.S., 2018. System for automatic gait analysis based on a single RGB-D camera. *PloS one*, 13(8), p.e0201728.
- Roy, B., Bhaumik, S. and Chakraborty, J.K., 2004. Detection of gait characteristic using image processing technique. *Trends Biomater. Artif. Organs*, 17(2), pp.6-16.
- Ryu, J. and Kim, D.H., 2017. Real-time gait subphase detection using an EMG signal graph matching (ESGM) algorithm based on EMG signals. *Expert Systems with Applications*, 85, pp.357-365.
- Sabatini, A.M., Martelloni, C., Scapellato, S. and Cavallo, F., 2005. Assessment of walking features from foot inertial sensing. *IEEE Transactions on biomedical engineering*, 52(3), pp.486-494.
- Senanayake, C.M. and Senanayake, S.A., 2010. Computational intelligent gait-phase detection system to identify pathological gait. *IEEE Transactions on Information Technology in Biomedicine*, 14(5), pp.1173-1179.
- Senanayake, C. and Senanayake, S.A., 2011. A computational method for reliable gait event detection and abnormality detection for feedback in rehabilitation. *Computer methods in biomechanics and biomedical engineering*, 14(10), pp.863-874.
- Sharma, N., Prakash, A., Sahi, A.K., Sharma, N. and Sharma, S., 2020. Multimodal sensor to measure the concurrent electrical and mechanical activity of muscles for controlling a hand prosthesis. *Instrumentation Science & Technology*, pp.1-18.
- Shultz, A.H., Mitchell, J.E., Truex, D., Lawson, B.E. and Goldfarb, M., 2013, May. Preliminary evaluation of a walking controller for a powered ankle prosthesis. In *2013 IEEE International Conference on Robotics and Automation* (pp. 4838-4843). IEEE.
- Shultz, A.H., Mitchell, J.E., Truex, D., Lawson, B.E., Ledoux, E. and Goldfarb, M., 2014, August. A walking controller for a powered ankle prosthesis. In *2014 36th Annual International Conference of the IEEE Engineering in Medicine and Biology Society* (pp. 6203-6206). IEEE.
- Shultz, A.H. and Goldfarb, M., 2018. A unified controller for walking on even and uneven terrain with a powered ankle prosthesis. *IEEE Transactions on Neural Systems and Rehabilitation Engineering*, 26(4), pp.788-797.

- Spanias, J.A., Simon, A.M., Finucane, S.B., Perreault, E.J. and Hargrove, L.J., 2018. Online adaptive neural control of a robotic lower limb prosthesis. *Journal of neural engineering*, 15(1), p.016015.
- Sugeno, M., 1985. *Industrial applications of fuzzy control*. Elsevier Science Inc.
- Sugeno, M. and Kang, G.T., 1988. Structure identification of fuzzy model. *Fuzzy sets and systems*, 28(1), pp.15-33.
- Sup, F., Varol, H.A., Mitchell, J., Withrow, T. and Goldfarb, M., 2008, October. Design and control of an active electrical knee and ankle prosthesis. In *2008 2nd IEEE RAS & EMBS International Conference on Biomedical Robotics and Biomechatronics* (pp. 523-528). IEEE.
- Tao, W., Liu, T., Zheng, R. and Feng, H., 2012. Gait analysis using wearable sensors. *Sensors*, 12(2), pp.2255-2283.
- Tao, Z., Ahn, H.J., Lian, C., Lee, K.H. and Lee, C.H., 2017. Design and optimization of prosthetic foot by using polylactic acid 3D printing. *Journal of Mechanical Science and Technology*, 31(5), pp.2393-2398.
- Taşar, B. and Gülten, A., 2017. EMG-Controlled Prosthetic Hand with Fuzzy Logic Classification Algorithm. *Modern Fuzzy Control Systems and Its Applications*, p.321.
- Team, P.C., 2015. Python: A dynamic, open source programming language. *Python Software Foundation*, 78.
- Truong, T.T. and Nguyen, T.K., 2021. Non-linear Behavior Assessment and Fatigue Analysis of Ankle Foot Orthosis by Finite Element Method. *Science and Technology Development Journal*, 24(S11), pp.SI25-SI31.
- Tucker, M.R., Olivier, J., Pagel, A., Bleuler, H., Bouri, M., Lambercy, O., del R Millán, J., Riener, R., Vallery, H. and Gassert, R., 2015. Control strategies for active lower extremity prosthetics and orthotics: a review. *Journal of neuroengineering and rehabilitation*, 12(1), p.1.
- Tyan, F., Chen, C.L., Tu, S.H. and Cooperation, S.L., 2009. Control of an Above Knee Prosthesis with MR Damper. In *International Automatic Control Conference, Taiwan*.
- Van Der Walt, S., Colbert, S.C. and Varoquaux, G., 2011. The NumPy array: a structure for efficient numerical computation. *Computing in science & engineering*, 13(2), pp.22-30.
- Varol, H.A., Sup, F. and Goldfarb, M., 2008, October. Real-time gait mode intent recognition of a powered knee and ankle prosthesis for standing and walking. In *2008 2nd IEEE RAS & EMBS International Conference on Biomedical Robotics and Biomechatronics* (pp. 66-72). IEEE.
- Verma, D., Dash, P., Bhaskar, S., Pal, R.P., Jain, K., Srivastava, R.P. and Hansraj, N., 2016. Disabled persons in India: a statistical profile 2016. *Ministry of Statistics and Programme Implementation, Government of India*.
- Versluys, R., Beyl, P., Van Damme, M., Desomer, A., Van Ham, R. and Lefeber, D., 2009. Prosthetic feet: State-of-the-art review and the importance of mimicking human ankle-foot biomechanics. *Disability and Rehabilitation: Assistive Technology*, 4(2), pp.65-75.
- Vrieling, A.H., Van Keeken, H.G., Schoppen, T., Otten, E., Halbertsma, J.P.K., Hof, A.L. and Postema, K., 2008. Uphill and downhill walking in unilateral lower limb amputees. *Gait & posture*, 28(2), pp.235-242.
- Wang, A.H. and Liu, J.W., 2007, November. A gait recognition method based on positioning human body joints. In *2007 International Conference on Wavelet Analysis and Pattern Recognition* (Vol. 3, pp. 1067-1071). IEEE.

- Wang, J., Kannape, O.A. and Herr, H.M., 2013, June. Proportional EMG control of ankle plantar flexion in a powered transtibial prosthesis. In *2013 IEEE 13th International Conference on Rehabilitation Robotics (ICORR)* (pp. 1-5). IEEE.
- Wang, L., Tan, T., Hu, W. and Ning, H., 2003. Automatic gait recognition based on statistical shape analysis. *IEEE transactions on image processing*, 12(9), pp.1120-1131.
- Wang, S.C., 2003. Artificial neural network. In *Interdisciplinary computing in java programming* (pp. 81-100). Springer, Boston, MA.
- Wang, W., Li, J., Li, W.D. and Sun, L.N., 2013. An echo-based gait phase determination method of lower limb prosthesis. In *Advanced Materials Research* (Vol. 706, pp. 629-634). Trans Tech Publications Ltd.
- Weerakkody, T.H., Lalitharatne, T.D. and Gopura, R.A.R.C., 2017. Adaptive foot in lower-limb prostheses. *Journal of Robotics*, 2017.
- Weiss, A., Brozgol, M., Dorfman, M., Herman, T., Shema, S., Giladi, N. and Hausdorff, J.M., 2013. Does the evaluation of gait quality during daily life provide insight into fall risk? A novel approach using 3-day accelerometer recordings. *Neurorehabilitation and neural repair*, 27(8), pp.742-752.
- Whittle, M.W., 2014. *Gait analysis: an introduction*. Butterworth-Heinemann.
- Winter, D.A., 1991. *Biomechanics and motor control of human gait: normal, elderly and pathological*.
- Winter, D.A., 2009. *Biomechanics and motor control of human movement*. John Wiley & Sons.
- Xiao, Z.G. and Menon, C., 2019. A review of force myography research and development. *Sensors*, 19(20), p.4557.
- Yang, J.F. and Winter, D.A., 1985. Surface EMG profiles during different walking cadences in humans. *Electroencephalography and clinical Neurophysiology*, 60(6), pp.485-491.
- Yang, L., Yang, B., Dong, H. and El Saddik, A., 2016. 3-D markerless tracking of human gait by geometric trilateration of multiple Kinects. *IEEE Systems Journal*, 12(2), pp.1393-1403.
- Yang, M., Zheng, H., Wang, H., McClean, S. and Newell, D., 2012. iGAIT: an interactive accelerometer based gait analysis system. *Computer methods and programs in biomedicine*, 108(2), pp.715-723.
- Ye, M., Yang, C., Stankovic, V., Stankovic, L. and Kerr, A., 2016. A depth camera motion analysis framework for tele-rehabilitation: Motion capture and person-centric kinematics analysis. *IEEE Journal of Selected Topics in Signal Processing*, 10(5), pp.877-887.
- Young, A.J., Kuiken, T.A. and Hargrove, L.J., 2014. Analysis of using EMG and mechanical sensors to enhance intent recognition in powered lower limb prostheses. *Journal of neural engineering*, 11(5), p.056021.
- Yuan, K., Zhu, J., Wang, Q. and Wang, L., 2011. Finite-state control of powered below-knee prosthesis with ankle and toe. *IFAC Proceedings Volumes*, 44(1), pp.2865-2870.
- Yun, X., Calusdian, J., Bachmann, E.R. and McGhee, R.B., 2012. Estimation of human foot motion during normal walking using inertial and magnetic sensor measurements. *IEEE transactions on Instrumentation and Measurement*, 61(7), pp.2059-2072.
- Zadeh, L.A., 1988. Fuzzy logic. *Computer*, 21(4), pp.83-93.
- Zagrodny, B., Ludwicki, M., Wojnicz, W., Mrozowski, J. and Awrejcewicz, J., 2018. Cooperation of mono-and bi-articular muscles: human lower limb. *Journal of musculoskeletal & neuronal interactions*, 18(2), p.176.

Zakria, M., Maqbool, H.F., Hussain, T., Awad, M.I., Mehryar, P., Iqbal, N. and Dehghani-Sanij, A.A., 2017, February. Heuristic based gait event detection for human lower limb movement. In *2017 IEEE EMBS International Conference on Biomedical & Health Informatics (BHI)* (pp. 337-340). IEEE.

Zesiewicz, T.A., 2019. Parkinson disease. *CONTINUUM: Lifelong Learning in Neurology*, 25(4), pp.896-918.

Zhang, F. and Huang, H., 2012. Source selection for real-time user intent recognition toward volitional control of artificial legs. *IEEE journal of biomedical and health informatics*, 17(5), pp.907-914.

Zhao, G., Liu, G., Li, H. and Pietikainen, M., 2006, April. 3D gait recognition using multiple cameras. In *7th International Conference on Automatic Face and Gesture Recognition (FGR06)* (pp. 529-534). IEEE.

Zhu, J., Wang, Q. and Wang, L., 2010, July. PANTOE 1: Biomechanical design of powered ankle-foot prosthesis with compliant joints and segmented foot. In *2010 IEEE/ASME International Conference on Advanced Intelligent Mechatronics* (pp. 31-36). IEEE.

Zou, Q., Ni, L., Wang, Q., Li, Q. and Wang, S., 2017. Robust gait recognition by integrating inertial and RGBD sensors. *IEEE transactions on cybernetics*, 48(4), pp.1136-1150.

LIST OF PUBLICATION

A) Journal Publications

1. Negi, S. and Sharma, N. (2022), "A standalone computing system to classify human foot movements using machine learning techniques for ankle-foot prosthesis control", *Computer Methods in Biomechanics and Biomedical Engineering*, 25(12), pp.1370-1380. [SCIE]
2. Negi, S., Sagar, U., Nautiyal, V.K. and Sharma, N. (2022), "Design and analysis of magnetorheological damper based ankle-foot prosthesis prototype", *Industrial Robot*, Vol. 49 No. 2, pp. 240-248. [SCIE]
3. Negi, S., Sharma, S. and Sharma, N. (2021), "FSR and IMU sensors-based human gait phase detection and its correlation with EMG signal for different terrain walk", *Sensor Review*, Vol. 41 No. 3, pp. 235-245. [SCIE]
4. Negi, S., Negi, P.C., Sharma, S. and Sharma, N. (2020), "Human locomotion classification for different terrains using machine learning techniques", *Critical Reviews™ in Biomedical Engineering*, 48(4). [Scopus]
5. Negi, S., CBS Negi, P., Sharma, S., and Sharma, N. (2020), "Electromyographic and acceleration signals-based gait phase analysis for multiple terrain classification using deep learning", *International Journal of Advanced Research in Engineering and Technology*, 11(6).

B) Conference/ Workshop

1. Negi, S., Garg, K., Prajapat, M., & Sharma, N. (2022), "A Standalone Real-Time Gait Phase Detection Using Fuzzy-Logic Implementation in Arduino Nano", *SN Computer Science*, 3(1), 1-7. [Scopus]
2. Negi, S., Negi, P. C., Singh, D. B. V., & Sharma, N. (2021), "Comparative Analysis of SVM and DNN for Multiple Terrain Classification Using Hybrid Sensor", In *Proceedings of Integrated Intelligence Enable Networks and Computing* (pp. 317-325). Springer, Singapore.
3. Sachin Negi, Shahrukh Khan, and Neeraj Sharma, An Energy-Efficient Insole: A Wearable Device for Gait Monitoring in Daily Life. *2019 World Conference on Access to Medical Products- achieving the SDGs 2030, 19-21 November 2019, Taj Hotel, New Delhi, India* [WHO- Poster presentation].