

# 9. Appendix A

## 9.1 Proof of Lemma 1.1

**Proof:** Let  $\mathbf{X} = [\underline{x}, \bar{x}]$ ,  $\mathbf{Y} = [\underline{y}, \bar{y}]$ , and  $\mathbf{Z} = [\underline{z}, \bar{z}]$

$$\begin{aligned} \text{(i)} \quad & (\mathbf{X} \oplus \mathbf{Y}) \ominus_{gH} (\mathbf{Y} \oplus \mathbf{Z}) \\ &= [\min\{(\underline{x} + \underline{y}) - (\underline{y} + \underline{z}), (\bar{x} + \bar{y}) - (\bar{y} + \bar{z})\}, \max\{(\underline{x} + \underline{y}) - (\underline{y} + \underline{z}), (\bar{x} + \bar{y}) - (\bar{y} + \bar{z})\}] \\ &= [\min\{\underline{x} - \underline{z}, \bar{x} - \bar{z}\}, \max\{\underline{x} - \underline{z}, \bar{x} - \bar{z}\}] = \mathbf{X} \ominus_{gH} \mathbf{Z}. \end{aligned}$$

(ii) Since,  $\mathbf{X} = \mathbf{Y} \oplus \mathbf{Z}$ ,

$$[\underline{x}, \bar{x}] = [\underline{y}, \bar{y}] \oplus [\underline{z}, \bar{z}] \implies \underline{x} = \underline{y} + \underline{z}, \bar{x} = \bar{y} + \bar{z} \implies \underline{x} - \underline{y} = \underline{z}, \bar{x} - \bar{y} = \bar{z}.$$

Hence,  $\mathbf{X} \ominus_{gH} \mathbf{Y} = \mathbf{Z}$ .

□

# 10. Appendix B

## 10.1 Proof of Lemma 1.2

**Proof:** Let  $\mathbf{W} = [\underline{w}, \bar{w}]$ ,  $\mathbf{Y} = [\underline{y}, \bar{y}]$  and  $\mathbf{Z} = [\underline{z}, \bar{z}]$ . From the  $gH$ -difference, we have the following four possible cases:

- (i) Given that  $\epsilon \preceq (\mathbf{W} \ominus_{gH} \mathbf{Y}) \ominus_{gH} \mathbf{Z} = [\underline{w} - \underline{y} - \underline{z}, \bar{w} - \bar{y} - \bar{z}]$ . Since  $\underline{w} - \underline{y} \geq \underline{z} + \epsilon$  and  $\bar{w} - \bar{y} \geq \bar{z} + \epsilon$ , we have  $\underline{z} + \epsilon \leq \bar{z} + \epsilon \leq \bar{w} - \bar{y}$ . This implies  $\underline{z} + \epsilon \leq \min\{\underline{w} - \underline{y}, \bar{w} - \bar{y}\}$ . Also,  $\bar{z} + \epsilon \leq \bar{w} - \bar{y} \leq \max\{\underline{w} - \underline{y}, \bar{w} - \bar{y}\}$ . Clearly we have  $[\underline{z} + \epsilon, \bar{z} + \epsilon] \preceq [\min\{\underline{w} - \underline{y}, \bar{w} - \bar{y}\}, \max\{\underline{w} - \underline{y}, \bar{w} - \bar{y}\}]$  and hence  $\mathbf{Z} \oplus \epsilon \preceq \mathbf{W} \ominus_{gH} \mathbf{Y}$ .
- (ii)  $(\mathbf{W} \ominus_{gH} \mathbf{Y}) \ominus_{gH} \mathbf{Z} = [\bar{w} - \bar{y} - \bar{z}, \underline{w} - \underline{y} - \underline{z}]$ . Thus, the proof is straightforward and identical to **Case (i)**.
- (iii)  $(\mathbf{W} \ominus_{gH} \mathbf{Y}) \ominus_{gH} \mathbf{Z} = [\bar{w} - \bar{y} - \underline{z}, \underline{w} - \underline{y} - \bar{z}]$ . Since  $\bar{w} - \bar{y} \geq \underline{z} + \epsilon$ ,  $\underline{w} - \underline{y} \geq \bar{z} + \epsilon$ , we have  $\underline{z} + \epsilon \leq \bar{z} + \epsilon \leq \underline{w} - \underline{y}$ . This implies  $\underline{z} + \epsilon \leq \min\{\underline{w} - \underline{y}, \bar{w} - \bar{y}\}$ . Also,  $\bar{z} + \epsilon \leq \underline{w} - \underline{y} \leq \max\{\underline{w} - \underline{y}, \bar{w} - \bar{y}\}$ . Clearly we have  $[\underline{z} + \epsilon, \bar{z} + \epsilon] \preceq [\min\{\underline{w} - \underline{y}, \bar{w} - \bar{y}\}, \max\{\underline{w} - \underline{y}, \bar{w} - \bar{y}\}]$  and hence  $\mathbf{Z} \oplus \epsilon \preceq \mathbf{W} \ominus_{gH} \mathbf{Y}$ .
- (iv)  $(\mathbf{W} \ominus_{gH} \mathbf{Y}) \ominus_{gH} \mathbf{Z} = [\underline{w} - \underline{y} - \bar{z}, \bar{w} - \bar{y} - \underline{z}]$ . Thus, the proof is identical to **Case (iii)**.

□

## 10.2 Proof of Lemma 1.3

**Proof:** Let  $\mathbf{X} = [\underline{x}, \bar{x}]$ ,  $\mathbf{Y} = [\underline{y}, \bar{y}]$ ,  $\mathbf{Z} = [\underline{z}, \bar{z}]$  and  $\mathbf{W} = [\underline{w}, \bar{w}]$ . Then,

$$\begin{aligned}
 & (\mathbf{X} \oplus \mathbf{Y}) \ominus_{gH} (\mathbf{Z} \oplus \mathbf{W}) \\
 &= [\min\{\underline{x} + \underline{y} - \underline{z} - \underline{w}, \bar{x} + \bar{y} - \bar{z} - \bar{w}\}, \max\{\underline{x} + \underline{y} - \underline{z} - \underline{w}, \bar{x} + \bar{y} - \bar{z} - \bar{w}\}] \\
 &= [\min\{\underline{x} - \underline{z} + \underline{y} - \underline{w}, \bar{x} - \bar{z} + \bar{y} - \bar{w}\}, \max\{\underline{x} - \underline{z} + \underline{y} - \underline{w}, \bar{x} - \bar{z} + \bar{y} - \bar{w}\}]. \quad (10.1)
 \end{aligned}$$

We have

$$\min\{\underline{x} - \underline{z} + \underline{y} - \underline{w}, \bar{x} - \bar{z} + \bar{y} - \bar{w}\} \geq \min\{\underline{x} - \underline{z}, \bar{x} - \bar{z}\} + \min\{\underline{y} - \underline{w}, \bar{y} - \bar{w}\} \quad (10.2)$$

$$\text{and } \max\{\underline{x} - \underline{z} + \underline{y} - \underline{w}, \bar{x} - \bar{z} + \bar{y} - \bar{w}\} \leq \max\{\underline{x} - \underline{z}, \bar{x} - \bar{z}\} + \max\{\underline{y} - \underline{w}, \bar{y} - \bar{w}\}. \quad (10.3)$$

By (10.2) and (10.3), from (10.1), we write

$$\begin{aligned}
& (\mathbf{X} \oplus \mathbf{Y}) \ominus_{gH} (\mathbf{Z} \oplus \mathbf{W}) \\
&= [\min\{\underline{x} - \underline{z} + \underline{y} - \underline{w}, \bar{x} - \bar{z} + \bar{y} - \bar{w}\}, \max\{\underline{x} - \underline{z} + \underline{y} - \underline{w}, \bar{x} - \bar{z} + \bar{y} - \bar{w}\}] \\
&\subseteq [\min\{\underline{x} - \underline{z}, \bar{x} - \bar{z}\} + \min\{\underline{y} - \underline{w}, \bar{y} - \bar{w}\}, \max\{\underline{x} - \underline{z}, \bar{x} - \bar{z}\} + \max\{\underline{y} - \underline{w}, \bar{y} - \bar{w}\}] \\
&= [\min\{\underline{x} - \underline{z}, \bar{x} - \bar{z}\}, \max\{\underline{x} - \underline{z}, \bar{x} - \bar{z}\}] + [\min\{\underline{y} - \underline{w}, \bar{y} - \bar{w}\}, \max\{\underline{y} - \underline{w}, \bar{y} - \bar{w}\}] \\
&= (\mathbf{X} \ominus_{gH} \mathbf{Z}) \oplus (\mathbf{Y} \ominus_{gH} \mathbf{W}).
\end{aligned}$$

□

### 10.3 Proof of Lemma 1.4

**Proof:** Let  $\mathbf{W} = [\underline{w}, \bar{w}]$ ,  $\mathbf{Y} = [\underline{y}, \bar{y}]$  and  $\mathbf{Z} = [\underline{z}, \bar{z}]$ . Then,  $-1 \odot \mathbf{W} = [-\bar{w}, -\underline{w}]$ ,  $-1 \odot \mathbf{Y} = [-\bar{y}, -\underline{y}]$ ,  $-1 \odot \mathbf{Z} = [-\bar{z}, -\underline{z}]$ .

From Definition of  $gH$ -difference of two intervals, we have

either  $-1 \odot \mathbf{W} \ominus_{gH} -1 \odot \mathbf{Y} = [\bar{y} - \bar{w}, \underline{y} - \underline{w}]$  or  $-1 \odot \mathbf{W} \ominus_{gH} -1 \odot \mathbf{Y} = [\underline{y} - \underline{w}, \bar{y} - \bar{w}]$ .

Then, one of the following holds true:

- (a)  $((-1 \odot \mathbf{W}) \ominus_{gH} (-1 \odot \mathbf{Y})) \ominus_{gH} (-1 \odot \mathbf{Z}) = [\bar{y} - \bar{w} + \bar{z}, \underline{y} - \underline{w} + \underline{z}]$
- (b)  $((-1 \odot \mathbf{W}) \ominus_{gH} (-1 \odot \mathbf{Y})) \ominus_{gH} (-1 \odot \mathbf{Z}) = [\underline{y} - \underline{w} + \underline{z}, \bar{y} - \bar{w} + \bar{z}]$
- (c)  $((-1 \odot \mathbf{W}) \ominus_{gH} (-1 \odot \mathbf{Y})) \ominus_{gH} (-1 \odot \mathbf{Z}) = [\underline{y} - \underline{w} + \bar{z}, \bar{y} - \bar{w} + \underline{z}]$
- (d)  $((-1 \odot \mathbf{W}) \ominus_{gH} (-1 \odot \mathbf{Y})) \ominus_{gH} (-1 \odot \mathbf{Z}) = [\bar{y} - \bar{w} + \underline{z}, \underline{y} - \underline{w} + \bar{z}]$ .

From this, we have

- (a)  $\mathbf{0} \ominus_{gH} \{((-1 \odot \mathbf{W}) \ominus_{gH} (-1 \odot \mathbf{Y})) \ominus_{gH} (-1 \odot \mathbf{Z})\} = [\underline{w} - \underline{y} - \underline{z}, \bar{w} - \bar{y} - \bar{z}]$
- (b)  $\mathbf{0} \ominus_{gH} \{((-1 \odot \mathbf{W}) \ominus_{gH} (-1 \odot \mathbf{Y})) \ominus_{gH} (-1 \odot \mathbf{Z})\} = [\bar{w} - \bar{y} - \bar{z}, \underline{w} - \underline{y} - \underline{z}]$
- (c)  $\mathbf{0} \ominus_{gH} \{((-1 \odot \mathbf{W}) \ominus_{gH} (-1 \odot \mathbf{Y})) \ominus_{gH} (-1 \odot \mathbf{Z})\} = [\bar{w} - \bar{y} - \underline{z}, \underline{w} - \underline{y} - \bar{z}]$
- (d)  $\mathbf{0} \ominus_{gH} \{((-1 \odot \mathbf{W}) \ominus_{gH} (-1 \odot \mathbf{Y})) \ominus_{gH} (-1 \odot \mathbf{Z})\} = [\underline{w} - \underline{y} - \bar{z}, \bar{w} - \bar{y} - \underline{z}]$ .

On the other hand,

- (a)  $(\mathbf{W} \ominus_{gH} \mathbf{Y}) \ominus_{gH} \mathbf{Z} = [\underline{w} - \underline{y} - \underline{z}, \bar{w} - \bar{y} - \bar{z}]$
- (b)  $(\mathbf{W} \ominus_{gH} \mathbf{Y}) \ominus_{gH} \mathbf{Z} = [\bar{w} - \bar{y} - \bar{z}, \underline{w} - \underline{y} - \underline{z}]$
- (c)  $(\mathbf{W} \ominus_{gH} \mathbf{Y}) \ominus_{gH} \mathbf{Z} = [\bar{w} - \bar{y} - \underline{z}, \underline{w} - \underline{y} - \bar{z}]$

$$(d) (\mathbf{W} \ominus_{gH} \mathbf{Y}) \ominus_{gH} \mathbf{Z} = [\underline{w} - \underline{y} - \underline{z}, \overline{w} - \overline{y} - \underline{z}].$$

Hence, the desired result follows.  $\square$

## 10.4 Proof of Lemma 1.5

**Proof:** Let  $\mathbf{X} = [\underline{x}, \overline{x}]$ ,  $\mathbf{Y} = [\underline{y}, \overline{y}]$  and  $\mathbf{Z} = [\underline{z}, \overline{z}]$ .

(i) Let us consider the following four representations:

$$(a) (\mathbf{X} \ominus_{gH} \mathbf{Y}) \ominus_{gH} \mathbf{Z} = [\underline{x} - \underline{y} - \underline{z}, \overline{x} - \overline{y} - \overline{z}],$$

$$(b) (\mathbf{X} \ominus_{gH} \mathbf{Y}) \ominus_{gH} \mathbf{Z} = [\underline{x} - \underline{y} - \overline{z}, \overline{x} - \overline{y} - \underline{z}],$$

$$(c) (\mathbf{X} \ominus_{gH} \mathbf{Y}) \ominus_{gH} \mathbf{Z} = [\overline{x} - \overline{y} - \underline{z}, \underline{x} - \underline{y} - \overline{z}],$$

$$(d) (\mathbf{X} \ominus_{gH} \mathbf{Y}) \ominus_{gH} \mathbf{Z} = [\overline{x} - \overline{y} - \overline{z}, \underline{x} - \underline{y} - \underline{z}].$$

• **Case 1.** Given that  $\mathbf{0} \preceq \mathbf{X} \ominus_{gH} \mathbf{Y}$ . Then we have

$$\begin{aligned} 0 &\leq \underline{x} - \underline{y} \text{ and } 0 \leq \overline{x} - \overline{y} \\ \implies 0 - \underline{z} &\leq \underline{x} - \underline{y} - \underline{z} \text{ and } 0 - \overline{z} \leq \overline{x} - \overline{y} - \overline{z} \\ \implies [0 - \underline{z}, 0 - \overline{z}] &\preceq [\underline{x} - \underline{y} - \underline{z}, \overline{x} - \overline{y} - \overline{z}]. \end{aligned} \quad (10.4)$$

So, from (10.4), we have  $\mathbf{0} \ominus_{gH} \mathbf{Z} \preceq (\mathbf{X} \ominus_{gH} \mathbf{Y}) \ominus_{gH} \mathbf{Z}$ .

• **Case 2.** Similarly, we will arrive at this conclusion (10.4). So, from (10.4), we have

$$\mathbf{0} \ominus_{gH} \mathbf{Z} \preceq (\mathbf{X} \ominus_{gH} \mathbf{Y}) \ominus_{gH} \mathbf{Z}.$$

• **Case 3.** This case can be proved by using the same steps as **Case 1**.

• **Case 4.** This case can be proved by using the same steps as **Case 2**.

(ii) Let  $\mathbf{W} = [\underline{w}, \overline{w}]$ . By the definition of  $gH$ -difference, there may be the following four cases.

$$(a) (\mathbf{X} \ominus_{gH} \mathbf{Y}) \ominus_{gH} \mathbf{W} = [\underline{x} - \underline{y} - \underline{w}, \overline{x} - \overline{y} - \overline{w}]$$

$$(b) (\mathbf{X} \ominus_{gH} \mathbf{Y}) \ominus_{gH} \mathbf{W} = [\underline{x} - \underline{y} - \overline{w}, \overline{x} - \overline{y} - \underline{w}]$$

$$(c) (\mathbf{X} \ominus_{gH} \mathbf{Y}) \ominus_{gH} \mathbf{W} = [\overline{x} - \overline{y} - \underline{w}, \underline{x} - \underline{y} - \overline{w}]$$

$$(d) (\mathbf{X} \ominus_{gH} \mathbf{Y}) \ominus_{gH} \mathbf{W} = [\overline{x} - \overline{y} - \overline{w}, \underline{x} - \underline{y} - \underline{w}].$$

The following two cases are needed to consider for the representation of these above four cases.

- **Case 1.** Since  $\mathbf{Z} \preceq \mathbf{X} \ominus_{gH} \mathbf{Y}$ , we have

$$\begin{aligned} & \underline{z} \leq \underline{x} - \underline{y} \text{ and } \bar{z} \leq \bar{x} - \bar{y} \\ \implies & \underline{z} - \underline{w} \leq \underline{x} - \underline{y} - \underline{w} \text{ and } \bar{z} - \bar{w} \leq \bar{x} - \bar{y} - \bar{w} \\ \implies & \text{either } [\underline{z} - \underline{w}, \bar{z} - \bar{w}] \preceq [\underline{x} - \underline{y} - \underline{w}, \bar{x} - \bar{y} - \bar{w}] \end{aligned} \quad (10.5)$$

$$\text{or } [\bar{z} - \bar{w}, \underline{z} - \underline{w}] \preceq [\bar{x} - \bar{y} - \bar{w}, \underline{x} - \underline{y} - \underline{w}] \quad (10.6)$$

From (10.5) and (10.6), we have  $\mathbf{Z} \ominus_{gH} \mathbf{W} \preceq (\mathbf{X} \ominus_{gH} \mathbf{Y}) \ominus_{gH} \mathbf{W}$ .

- **Case 2.** Similarly, at the last step, we have

$$\text{either } [z - w, \bar{z} - \bar{w}] \preceq [\bar{x} - \bar{y} - w, \underline{x} - \underline{y} - \bar{w}] \quad (10.7)$$

$$\text{or } [\bar{z} - \bar{w}, z - w] \preceq [\underline{x} - \underline{y} - \bar{w}, \bar{x} - \bar{y} - w] \quad (10.8)$$

From (10.7) and (10.8), we have  $\mathbf{Z} \ominus_{gH} \mathbf{W} \preceq (\mathbf{X} \ominus_{gH} \mathbf{Y}) \ominus_{gH} \mathbf{W}$ .

- (iii) Given that  $\mathbf{X} \ominus_{gH} \mathbf{Y} \preceq [L, L]$ . From the formula of  $gH$ -difference of intervals,

$$\begin{aligned} & \underline{x} - \underline{y} \leq L \text{ and } \bar{x} - \bar{y} \leq L \\ \implies & -L \leq \underline{y} - \underline{x}, -L \leq \bar{y} - \bar{x} \\ \implies & \text{either } [-L, -L] \preceq [\underline{y} - \underline{x}, \bar{y} - \bar{x}] \\ & \text{or } [-L, -L] \preceq [\bar{y} - \bar{x}, \underline{y} - \underline{x}]. \end{aligned}$$

Hence,  $[-L, -L] \preceq \mathbf{Y} \ominus_{gH} \mathbf{X}$ .

- (iv) Given that  $[-\gamma, -\gamma] \preceq \mathbf{X} \ominus_{gH} \mathbf{Y}$ . From the formula of  $gH$ -difference of intervals,

$$\begin{aligned} & -\gamma \leq \underline{x} - \underline{y} \text{ and } -\gamma \leq \bar{x} - \bar{y} \\ \implies & \underline{y} - \gamma \leq \underline{x} \text{ and } \bar{y} - \gamma \leq \bar{x} \\ \implies & [\underline{y} - \gamma, \bar{y} - \gamma] \preceq [\underline{x}, \bar{x}]. \end{aligned}$$

Hence,  $\mathbf{Y} \ominus_{gH} [\gamma, \gamma] \preceq \mathbf{X}$ .

- (v) Given that  $\mathbf{Z} \preceq \mathbf{X} \oplus \mathbf{Y}$ . Then,

$$\begin{aligned} & [z, \bar{z}] \preceq [\underline{x}, \bar{x}] \oplus [\underline{y}, \bar{y}] \\ \implies & z \leq \underline{x} + \underline{y}, \bar{z} \leq \bar{x} + \bar{y} \\ \implies & \underline{z} - \underline{y} \leq \underline{x}, \bar{z} - \bar{y} \leq \bar{x} \\ \implies & [\underline{z} - \underline{y}, \bar{z} - \bar{y}] \preceq [\underline{x}, \bar{x}]. \end{aligned}$$

Hence,  $\mathbf{Z} \ominus_{gH} \mathbf{Y} \preceq \mathbf{X}$ .

□

## 10.5 Proof of Lemma 3.1

**Proof:** Let  $y^\top \odot \widehat{\mathbf{C}} = \mathbf{D}$  and  $\mathbf{D} = [\underline{d}, \bar{d}]$ . Note that

$$\|\mathbf{D}\|_{I(\mathbb{R})} = \max\{|\underline{d}|, |\bar{d}|\}. \quad (10.9)$$

On the other hand,

$$\begin{aligned} \|\mathbf{D}\|_{I(\mathbb{R})} &= \|y_1 \odot \mathbf{C}_1 \oplus y_2 \odot \mathbf{C}_2 \oplus \cdots \oplus y_n \odot \mathbf{C}_n\|_{I(\mathbb{R})} \\ &\leq \|y_1 \odot \mathbf{C}_1\|_{I(\mathbb{R})} + \|y_2 \odot \mathbf{C}_2\|_{I(\mathbb{R})} + \cdots + \|y_n \odot \mathbf{C}_n\|_{I(\mathbb{R})} \\ &= |y_1| \|\mathbf{C}_1\|_{I(\mathbb{R})} \oplus |y_2| \|\mathbf{C}_2\|_{I(\mathbb{R})} + \cdots + |y_n| \|\mathbf{C}_n\|_{I(\mathbb{R})} \\ &\leq \|y\| \sum_{i=1}^n \|\mathbf{C}_i\|_{I(\mathbb{R})} \\ &= \|y\| \|\widehat{\mathbf{C}}\|_{I(\mathbb{R})^n}. \end{aligned} \quad (10.10)$$

Then, taking into account (10.9) and (10.10), we obtain

$$\begin{aligned} |\underline{d}| &\leq \|y\| \|\widehat{\mathbf{C}}\|_{I(\mathbb{R})^n} \text{ and } |\bar{d}| \leq \|y\| \|\widehat{\mathbf{C}}\|_{I(\mathbb{R})^n} \\ \implies -\|y\| \|\widehat{\mathbf{C}}\|_{I(\mathbb{R})^n} &\leq \underline{d} \text{ and } -\|y\| \|\widehat{\mathbf{C}}\|_{I(\mathbb{R})^n} \leq \bar{d} \\ \implies -\|y\| \|\widehat{\mathbf{C}}\|_{I(\mathbb{R})^n} &\leq |\underline{d}| \text{ and } -\|y\| \|\widehat{\mathbf{C}}\|_{I(\mathbb{R})^n} \leq |\bar{d}| \\ \implies -\|y\| \|\widehat{\mathbf{C}}\|_{I(\mathbb{R})^n} &\leq \max\{|\underline{d}|, |\bar{d}|\} \\ \implies -\|y\| \|\widehat{\mathbf{C}}\|_{I(\mathbb{R})^n} &\leq \|\mathbf{D}\|_{I(\mathbb{R})} \end{aligned}$$

Thus, we arrived at the desired result.

□

# 11. Appendix C

## 11.1 Proof of Lemma 1.6

**Proof:** Let  $\mathbf{Q} = [\underline{q}, \bar{q}]$ ,  $\mathbf{C} = [\underline{c}, \bar{c}]$ ,  $\mathbf{R} = [\underline{r}, \bar{r}]$ . From Definition of  $gH$ -difference of two intervals, we have

$$\begin{aligned}
 & \inf\{\mathbf{Q}, \mathbf{R} \oplus \mathbf{C}\} \ominus_{gH} \mathbf{C} \\
 &= \inf\{[\underline{q}, \bar{q}], [\underline{r} + \underline{c}, \bar{r} + \bar{c}]\} \ominus_{gH} [\underline{c}, \bar{c}] \\
 &= [\inf\{\underline{q}, \underline{r} + \underline{c}\}, \inf\{\bar{q}, \bar{r} + \bar{c}\}] \ominus_{gH} [\underline{c}, \bar{c}] \\
 &= [\min\{\inf\{\underline{q}, \underline{r} + \underline{c}\} - \underline{c}, \inf\{\bar{q}, \bar{r} + \bar{c}\} - \bar{c}\}, \max\{\inf\{\underline{q}, \underline{r} + \underline{c}\} - \underline{c}, \inf\{\bar{q}, \bar{r} + \bar{c}\} - \bar{c}\}],
 \end{aligned} \tag{11.1}$$

and

$$\begin{aligned}
 & \inf\{\mathbf{Q} \ominus_{gH} \mathbf{C}, \mathbf{R}\} \\
 &= \inf\{[\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}], [\underline{r}, \bar{r}]\} \\
 &= [\inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \underline{r}\}, \inf\{\max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \bar{r}\}].
 \end{aligned} \tag{11.2}$$

In order to show  $\inf\{\mathbf{Q}, \mathbf{R} \oplus \mathbf{C}\} \ominus_{gH} \mathbf{C} \subseteq \inf\{\mathbf{Q} \ominus_{gH} \mathbf{C}, \mathbf{R}\}$ , we first need to show that

$$\inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \underline{r}\} \leq \min\{\inf\{\underline{q}, \underline{r} + \underline{c}\} - \underline{c}, \inf\{\bar{q}, \bar{r} + \bar{c}\} - \bar{c}\}, \tag{11.3}$$

and

$$\max\{\inf\{\underline{q}, \underline{r} + \underline{c}\} - \underline{c}, \inf\{\bar{q}, \bar{r} + \bar{c}\} - \bar{c}\} \leq \inf\{\max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \bar{r}\}. \tag{11.4}$$

To show (11.3), we first have that

$$\begin{aligned}
 & \inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \underline{r}\} \\
 &\leq \min\{\underline{q} - \underline{c}, \underline{r}\} \\
 &= \inf\{\underline{q} - \underline{c}, \underline{r}\} \\
 &\leq \inf\{\underline{q}, \underline{r} + \underline{c}\} - \inf\{\underline{c}, \underline{c}\} \\
 &= \inf\{\underline{q}, \underline{r} + \underline{c}\} - \underline{c}.
 \end{aligned} \tag{11.5}$$

Similarly,

$$\inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \underline{r}\} \leq \inf\{\bar{q}, \bar{r} + \bar{c}\} - \bar{c}. \quad (11.6)$$

Combining (11.5) and (11.6), we have

$$\begin{aligned} & \inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \underline{r}\} \\ & \leq \min\{\inf\{\underline{q}, \underline{r} + \underline{c}\} - \underline{c}, \inf\{\bar{q}, \bar{r} + \bar{c}\} - \bar{c}\}. \end{aligned} \quad (11.7)$$

Note that

$$\inf\{\underline{q}, \underline{r} + \underline{c}\} - \underline{c} \leq \underline{q} - \underline{c} \leq \max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} \quad (11.8)$$

and

$$\inf\{\underline{q}, \underline{r} + \underline{c}\} - \underline{c} \leq \underline{r} \leq \bar{r}. \quad (11.9)$$

From (11.8) and (11.9), we have

$$\inf\{\underline{q}, \underline{r} + \underline{c}\} - \underline{c} \leq \inf\{\max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \bar{r}\}. \quad (11.10)$$

Similarly,

$$\inf\{\bar{q}, \bar{r} + \bar{c}\} - \bar{c} \leq \inf\{\max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \bar{r}\}. \quad (11.11)$$

Combining (11.10) and (11.11), we have

$$\max\{\inf\{\underline{q}, \underline{r} + \underline{c}\} - \underline{c}, \inf\{\bar{q}, \bar{r} + \bar{c}\} - \bar{c}\} \leq \inf\{\max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \bar{r}\}. \quad (11.12)$$

Accumulating (11.7) and (11.12), we have

$$\begin{aligned} & \inf\{\mathbf{Q}, \mathbf{R} \oplus \mathbf{C}\} \ominus_{gH} \mathbf{C} \\ & = [\min\{\inf\{\underline{q}, \underline{r} + \underline{c}\} - \underline{c}, \inf\{\bar{q}, \bar{r} + \bar{c}\} - \bar{c}\}, \max\{\inf\{\underline{q}, \underline{r} + \underline{c}\} - \underline{c}, \inf\{\bar{q}, \bar{r} + \bar{c}\} - \bar{c}\}] \\ & \subseteq [\inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \underline{r}\}, \inf\{\max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \bar{r}\}] \\ & = \inf\{\mathbf{Q} \ominus_{gH} \mathbf{C}, \mathbf{R}\}. \end{aligned}$$

□

## 11.2 Proof of Lemma 1.7

**Proof:** Let  $\mathbf{Q} = [\underline{q}, \bar{q}]$ ,  $\mathbf{C} = [\underline{c}, \bar{c}]$ ,  $\mathbf{R} = [\underline{r}, \bar{r}]$ . From Definition of  $gH$ -difference of two intervals, we have

$$\begin{aligned} & \inf\{\mathbf{Q} \ominus_{gH} \mathbf{C}, \mathbf{R}\} \ominus_{gH} \mathbf{R} \\ &= \inf\{[\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}], [\underline{r}, \bar{r}]\} \ominus_{gH} [\underline{r}, \bar{r}] \\ &= [\min\{\inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \underline{r}\} - \underline{r}, \inf\{\max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \bar{r}\} - \bar{r}\}, \\ & \quad \max\{\inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \underline{r}\} - \underline{r}, \inf\{\max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \bar{r}\} - \bar{r}\}] \end{aligned}$$

On the other hand, from the similar  $gH$ -difference definition,

$$\begin{aligned} & \inf\{(\mathbf{Q} \ominus_{gH} \mathbf{C}) \ominus_{gH} \mathbf{R}, 0\} \\ &= [\inf\{\min\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} - \underline{r}, \max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} - \bar{r}\}, 0\}, \\ & \quad \inf\{\max\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} - \underline{r}, \max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} - \bar{r}\}, 0\}] \end{aligned}$$

Next, we can have two following inequalities:

$$\begin{aligned} & \inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \underline{r}\} - \underline{r} \\ &= \inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \underline{r}\} - \inf\{\underline{r}, \underline{r}\} \\ &\leq \inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} - \underline{r}, 0\} \\ &\leq \min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} - \underline{r} \\ &\leq \max\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} - \underline{r}, \max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} - \bar{r}\}. \end{aligned} \tag{11.13}$$

and

$$\begin{aligned} & \inf\{\max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \underline{r}\} - \underline{r} \\ &= \inf\{\max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \underline{r}\} - \inf\{\underline{r}, \underline{r}\} \\ &\leq \inf\{\max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} - \underline{r}, 0\} \\ &\leq \max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} - \underline{r} \\ &\leq \max\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} - \underline{r}, \max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} - \bar{r}\}. \end{aligned} \tag{11.14}$$

By combining (11.13) and (11.14), we have

$$\begin{aligned} & \max\{\inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \underline{r}\} - \underline{r}, \inf\{\max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \bar{r}\} - \bar{r}\} \\ &\leq \max\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} - \underline{r}, \max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} - \bar{r}\}. \end{aligned} \tag{11.15}$$

Next, we can make other two inequalities:

$$\begin{aligned}
& \inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \underline{r}\} - \underline{r} \\
&= \inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \underline{r}\} - \inf\{\underline{r}, \underline{r}\} \\
&\leq \inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} - \underline{r}, 0\} \\
&\leq 0.
\end{aligned} \tag{11.16}$$

and

$$\begin{aligned}
& \inf\{\max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}\} - \bar{r} \\
&= \inf\{\max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \bar{r}\} - \inf\{\bar{r}, \bar{r}\} \\
&\leq \inf\{\max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} - \bar{r}, 0\} \\
&\leq 0.
\end{aligned} \tag{11.17}$$

By combining (11.16) and (11.17), we have

$$\max\{\inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \underline{r}\} - \underline{r}, \inf\{\max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \bar{r}\} - \bar{r}\} \leq 0. \tag{11.18}$$

Therefore, accumulating (11.15) and (11.18), we have

$$\begin{aligned}
& \max\{\inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \underline{r}\} - \underline{r}, \inf\{\max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \bar{r}\} - \bar{r}\} \\
&\leq \inf\{\max\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} - \underline{r}, \max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} - \bar{r}\}, 0\}.
\end{aligned} \tag{11.19}$$

Now, it is remaining to show that

$$\begin{aligned}
& \inf\{\min\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} - \underline{r}, \max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}\} - \bar{r}, 0\} \\
&\leq \min\{\inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \underline{r}\} - \underline{r}, \inf\{\max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \bar{r}\} - \bar{r}\}.
\end{aligned} \tag{11.20}$$

For this, we consider the following inequalities:

$$\begin{aligned}
& \inf\{\min\{\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} - \underline{r}, \max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}\} - \bar{r}\}, 0\} \\
&\leq \inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \underline{r}\} - \underline{r} \\
&\leq \inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \underline{r}\} - \inf\{\underline{r}, \bar{r}\} \\
&= \inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \underline{r}\} - \underline{r}.
\end{aligned} \tag{11.21}$$

and

$$\begin{aligned}
& \inf\{\min\{\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} - \underline{r}, \max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} - \bar{r}\}\}, 0\} \\
& \leq \inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \underline{r}\}, 0\} \\
& \leq \inf\{\max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \bar{r}\} - \inf\{\bar{r}, \bar{r}\} \\
& = \inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \bar{r}\} - \bar{r}
\end{aligned} \tag{11.22}$$

From (11.21) and (11.22), we have

$$\begin{aligned}
& \inf\{\min\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\} - \underline{r}, \max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}\} - \bar{r}, 0\} \\
& \leq \min\{\inf\{\min\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \underline{r}\} - \underline{r}, \inf\{\max\{\underline{q} - \underline{c}, \bar{q} - \bar{c}\}, \bar{r}\} - \bar{r}\}.
\end{aligned} \tag{11.23}$$

Again, from (11.19) and (11.23), we have

$$\inf\{\mathbf{Q} \ominus_{gH} \mathbf{C}, \mathbf{R}\} \ominus_{gH} \mathbf{R} \subseteq \inf\{(\mathbf{Q} \ominus_{gH} \mathbf{C}) \ominus_{gH} \mathbf{R}, 0\}.$$

□

### 11.3 Proof of Lemma 1.8

**Proof:** Let  $\mathbf{Q} = [\underline{q}, \bar{q}]$ ,  $\mathbf{R} = [\underline{r}, \bar{r}]$ ,  $\mathbf{S} = [\underline{s}, \bar{s}]$ . Then, we have

$$\begin{aligned}
& -\epsilon \preceq (\mathbf{Q} \ominus_{gH} \mathbf{R}) \ominus_{gH} \mathbf{S} \\
\implies & -\epsilon \preceq [\min\{\underline{q} - \underline{r}, \bar{q} - \bar{r}\}, \max\{\underline{q} - \underline{r}, \bar{q} - \bar{r}\}] \ominus_{gH} [\underline{s}, \bar{s}] \\
\implies & -\epsilon \preceq [\min\{\min\{\underline{q} - \underline{r}, \bar{q} - \bar{r}\} - \underline{s}, \max\{\underline{q} - \underline{r}, \bar{q} - \bar{r}\} - \bar{s}\}, \\
& \quad \max\{\min\{\underline{q} - \underline{r}, \bar{q} - \bar{r}\} - \underline{s}, \max\{\underline{q} - \underline{r}, \bar{q} - \bar{r}\} - \bar{s}\}] \\
\implies & -\epsilon \leq \min\{\underline{q} - \underline{r}, \bar{q} - \bar{r}\} - \underline{s} \textbf{ and } -\epsilon \leq \max\{\underline{q} - \underline{r}, \bar{q} - \bar{r}\} - \bar{s} \\
\implies & [\underline{s}, \bar{s}] \preceq [\min\{\underline{q} - \underline{r}, \bar{q} - \bar{r}\}, \max\{\underline{q} - \underline{r}, \bar{q} - \bar{r}\}] \oplus \epsilon \\
\implies & \mathbf{S} \preceq (\mathbf{Q} \ominus_{gH} \mathbf{R}) \oplus \epsilon.
\end{aligned}$$

□

### 11.4 Proof of Lemma 1.9

**Proof:** Let  $\mathbf{\Upsilon} = [\underline{\gamma}, \bar{\gamma}]$ ,  $\mathbf{\Upsilon}_1 = [\underline{\gamma}_1, \bar{\gamma}_1]$ ,  $\mathbf{\Upsilon}_2 = [\underline{\gamma}_2, \bar{\gamma}_2]$ .

(i) We note that

$$\begin{aligned}
& \liminf_{z \rightarrow \bar{z}} \{-1 \odot \Upsilon(z)\} \\
&= \liminf_{z \rightarrow \bar{z}} \{-1 \odot [\underline{\gamma}(z), \bar{\gamma}(z)]\} \\
&= \liminf_{z \rightarrow \bar{z}} [-\bar{\gamma}(z), -\underline{\gamma}(z)] \\
&= [\liminf_{z \rightarrow \bar{z}}(-\bar{\gamma}(z)), \liminf_{z \rightarrow \bar{z}}(-\underline{\gamma}(z))] \\
&= [-\limsup_{z \rightarrow \bar{z}} \bar{\gamma}(z), -\limsup_{z \rightarrow \bar{z}} \underline{\gamma}(z)] \\
&= -1 \odot [\limsup_{z \rightarrow \bar{z}} \underline{\gamma}(z), \limsup_{z \rightarrow \bar{z}} \bar{\gamma}(z)] \\
&= -1 \odot \limsup_{z \rightarrow \bar{z}} \Upsilon(z).
\end{aligned}$$

(ii) Note that

$$\begin{aligned}
& \liminf_{z \rightarrow \bar{z}} \{\Upsilon_1(z) \ominus_{gH} \Upsilon_2(z)\} \\
&= \liminf_{z \rightarrow \bar{z}} \{[\min\{\underline{\gamma}_1(z) - \underline{\gamma}_2(z), \bar{\gamma}_1(z) - \bar{\gamma}_2(z)\}, \max\{\underline{\gamma}_1(z) - \underline{\gamma}_2(z), \bar{\gamma}_1(z) - \bar{\gamma}_2(z)\}]\}.
\end{aligned} \tag{11.24}$$

provided  $\lim_{z \rightarrow \bar{z}} \Upsilon_2(z)$ . We know if  $\lim_{z \rightarrow \bar{z}} \underline{\gamma}_2(z)$  exists, then

$$\liminf_{z \rightarrow \bar{z}} \{\underline{\gamma}_1(z) - \underline{\gamma}_2(z)\} = \liminf_{z \rightarrow \bar{z}} \{\underline{\gamma}_1(z) + (-\underline{\gamma}_2(z))\} = \liminf_{z \rightarrow \bar{z}} \underline{\gamma}_1(z) - \lim_{z \rightarrow \bar{z}} \underline{\gamma}_2(z). \tag{11.25}$$

Similarly, if  $\lim_{z \rightarrow \bar{z}} \bar{\gamma}_2(z)$  exists, then

$$\liminf_{z \rightarrow \bar{z}} \{\bar{\gamma}_1(z) - \bar{\gamma}_2(z)\} = \liminf_{z \rightarrow \bar{z}} \bar{\gamma}_1(z) - \lim_{z \rightarrow \bar{z}} \bar{\gamma}_2(z). \tag{11.26}$$

With the help of (11.25), (11.26), from (11.24), we have

$$\begin{aligned}
& [\min\{\liminf_{z \rightarrow \bar{z}} \underline{\gamma}_1(z) - \lim_{z \rightarrow \bar{z}} \underline{\gamma}_2(z), \liminf_{z \rightarrow \bar{z}} \bar{\gamma}_1(z) - \lim_{z \rightarrow \bar{z}} \bar{\gamma}_2(z)\}, \\
& \max\{\liminf_{z \rightarrow \bar{z}} \underline{\gamma}_1(z) - \lim_{z \rightarrow \bar{z}} \underline{\gamma}_2(z), \liminf_{z \rightarrow \bar{z}} \bar{\gamma}_1(z) - \lim_{z \rightarrow \bar{z}} \bar{\gamma}_2(z)\}] \\
&= \liminf_{z \rightarrow \bar{z}} \Upsilon_1(z) \ominus_{gH} \lim_{z \rightarrow \bar{z}} \Upsilon_2(z).
\end{aligned}$$

□

## 12. Appendix D

**Example 12.0.1** We consider a ZDT1-type [194] SOP involving a set of 100 objective functions, given by

$$F(x) := \{f^1(x), f^2(x), \dots, f^{100}(x)\},$$

where, for each  $i \in [100]$ ,  $f^i : \mathbb{R}^n \rightarrow \mathbb{R}^2$  is given by

$$f^i(x) = \begin{pmatrix} f_1(x) + (0.05 + 0.05 * (\cos^{16}(\frac{4\pi i}{100}))) \cos(\frac{2\pi i}{100}) \\ g(x)h(f_1(x), g(x)) + (0.05 + 0.05 * (\cos^{16}(\frac{4\pi i}{100}))) \sin(\frac{2\pi i}{100}) \end{pmatrix}$$

with

$$\begin{aligned} f_1(x) &= x_1 \\ g(x) &= 1 + 9 \sum_{i=2}^n x_i \\ h(f_1, g) &= 1 - \sqrt{\frac{f_1}{g}}. \end{aligned}$$

We consider 4 different versions of this example for  $n = 2, 5, 8, 10$ . For randomly sampling 100 initial points, we consider the box region  $\mathcal{S}$  of the form  $[L, U]$ , where  $L = [0, 0, 0, \dots, 0]$  and  $U = [1, 1, 1, \dots, 1]$ .

**Example 12.0.2** We consider ZDT4-type [194] SOP involving  $n$ -variables and a set of 100 objective functions, given by

$$F(x) = \{f^1(x), f^2(x), \dots, f^{100}(x)\}.$$

where, for each  $i \in [100]$ , the objective function of the SOP,  $f^i : \mathbb{R}^n \rightarrow \mathbb{R}^2, n = 10$ , is given by

$$f^i(x) = \begin{pmatrix} f_1(x) + (1 + (\cos(\frac{4i\pi}{100}))^{16} \cos(\frac{2i\pi}{100})) \\ g(x)h(f_1(x)g(x)) + (1 + (\cos(\frac{4i\pi}{100}))^{16} \sin(\frac{2i\pi}{100})), \end{pmatrix}$$

with

$$\begin{aligned} f_1(x) &= x_1 \\ g(x) &= 1 + 10(n - 1) + \sum_{i=2}^n (x_i^2 - 10 \cos(4\pi x_i)) \end{aligned}$$

$$h_1(f_1, g) = 1 - \sqrt{\frac{f_1}{g}},$$

For randomly sampling 100 initial points, we consider the box region  $\mathcal{S}$  of the form  $[L, U]$ , where  $L = [0, 0, \dots, 0]$ , and  $U = [1, 1, \dots, 1]$ .

**Example 12.0.3** Motivated from Ex.4.3 in [93], we consider a SOP involving a set of 100 objective functions, given by

$$F(x) := \{f^1(x), f^2(x), \dots, f^{125}(x)\},$$

where, for each  $i \in [125]$ ,  $f^i : \mathbb{R}^2 \rightarrow \mathbb{R}^4$  is given by

$$f^i(x) = g(x) + (x_1 + \frac{1}{10} \sin(20\phi_{1i}) \sin(20\phi_{2i})) \begin{pmatrix} \cos(\phi_{1i}) \\ \sin(\phi_{1i}) \cos(\phi_{2i}) \\ \sin(\phi_{1i}) \sin(\phi_{2i}) \cos(\phi_{3i}) \\ \sin(\phi_{1i}) \sin(\phi_{2i}) \sin(\phi_{3i}) \end{pmatrix}.$$

with

$$g(x) = 100(x_1^2 + x_2^2 - 9)^2 \begin{pmatrix} |x_1| \\ |x_2| \\ |x_1 + x_2| \\ |x_1| \end{pmatrix}.$$

For randomly sampling 100 initial points, we consider the box region  $\mathcal{S}$  of the form  $[L, U]$ , where  $L = [-10, -10]$  and  $U = [10, 10]$ , and the set  $\{(\phi_{1i}, \phi_{2i}, \phi_{3i}) : i \in [125]\}$  is an enumeration of the set  $\{\frac{2\pi}{5}(i_1 - 1) : i_1 \in [5]\} \times \{\frac{2\pi}{5}(i_2 - 1) : i_2 \in [5]\} \times \{\frac{2\pi}{5}(i_3 - 1) : i_3 \in [5]\}$ .

**Example 12.0.4** We consider DTLZ1 [37] type SOP involving a set of 100 objective functions, given by

$$F(x) := \{f^1(x), f^2(x), \dots, f^{100}(x)\},$$

where, for each  $i \in [100]$ ,  $f^i : \mathbb{R}^6 \rightarrow \mathbb{R}^4$ , is given by

$$f^i(x) = h(x) + \begin{pmatrix} \cos(\phi_i) \sin(\psi_i) \\ \sin(\phi_i) \sin(\psi_i) \\ (\cos(\psi_i) + \log(\tan(\frac{\psi_i}{2}))) + 0.2 * \phi_i \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

with

$$h(x) = \begin{bmatrix} (1 + g(x_M))x_1x_2 \dots x_{M-1} \\ (1 + g(x_M))x_1x_2 \dots (1 - x_{M-1}) \\ \vdots \\ (1 + g(x_M))\frac{1}{2}x_1(1 - x_2) \\ \frac{1}{2}(1 - x_1)(1 + g(x_M)). \end{bmatrix}$$

and

$$g(x_M) = 100(|x_M| + \sum_{x_i \in x_M} (x_i - 0.5)^2 - \cos(20 * \pi * (x_i - 0.5))).$$

Here, last  $k = n - M + 1$  variables are represented as  $x_M$  and the set  $\{(\phi_i, \psi_i) : i \in [100]\}$  is an enumeration of the set  $\{\frac{\pi}{5}(j - 1) : j \in [10]\} \times \{\frac{\pi}{5}(\ell - 1) : \ell \in [10]\}$ . For randomly sampling 100 initial points, we consider the box region  $\mathcal{S}$  of the form  $[L, U]$ , where  $L = [0, 0, \dots, 0]$ , and  $U = [1, 1, \dots, 1]$ .

**Example 12.0.5** We consider DTLZ3 [37] type SOP, involving a set of 100 objective functions, given by

$$F(x) := \{f^1(x), f^2(x), \dots, f^{100}(x)\},$$

where for each  $i \in [100]$ ,  $f^i : \mathbb{R}^n \rightarrow \mathbb{R}^m$ ,  $n = 5$ ,  $m = 4$ , is given by

$$f^i(x) = h(x) + \begin{pmatrix} \operatorname{sech}(\phi_i) \cos(\phi_2) \\ \operatorname{sech}(\phi_i) \sin(\psi_i) \\ \phi_i - \operatorname{tanh}(\phi_i) \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

with

$$h(x) = \begin{bmatrix} (1 + g(x_M)) \cos(\frac{x_1\pi}{2}) \dots \cos(\frac{x_{M-2}\pi}{2}) \cos(\frac{x_{M-1}\pi}{2}) \\ (1 + g(x_M)) \cos(\frac{x_1\pi}{2}) \dots \cos(\frac{x_{M-2}\pi}{2}) \sin(\frac{x_{M-1}\pi}{2}) \\ (1 + g(x_M)) \cos(\frac{x_1\pi}{2}) \cos(\frac{x_1\pi}{2}) \\ \vdots \\ (1 + g(x_M)) \sin(\frac{x_1\pi}{2}). \end{bmatrix}$$

and

$$g(x_M) = 100 * (|x_M| + \sum_{x_i \in x_M} (x_i - 0.5)^2 - \cos(20 * \pi * (x_i - 0.5)))$$

$$0 \leq x_i \leq 1, \text{ for } i = 1, 2, \dots, n$$

Last  $k = n - M + 1$  variables are represented as  $x_M$  and the set  $\{(\phi_i, \psi_i) : i \in [100]\}$  is an enumeration of the set  $\{\frac{\pi}{5}(j - 1) : j \in [10] \times \frac{\pi}{5}(l - 1) : l \in [10]\}$ , and for randomly sampling 100 initial points, we consider the box region  $\mathcal{S}$  of the form  $[L, U]$ , where  $L = [0, 0, \dots, 0]$ , and  $U = [1, 1, \dots, 1]$ .

**Example 12.0.6** We consider FDSa [56] type SOP involving a set of 100 objective functions, given by

$$F(x) := \{f^1(x), f^2(x), \dots, f^{100}(x)\},$$

where, for each  $i \in [100]$ ,  $f^i : \mathbb{R}^2 \rightarrow \mathbb{R}^3$  is given by

$$f^i(x) = \begin{pmatrix} G_1(x) + (1 + \cos(\phi_i) \cos(\psi_i)) \\ G_2(x) + (1 + \cos(\phi_i) \sin(\psi_i)) \\ G_3(x) + \sin(\phi_i) \end{pmatrix}$$

with

$$G_1(x) = \frac{1}{n^2} \sum_{i=1}^n i(x_i - i)^4$$

$$G_2(x) = \exp\left(\sum_{i=1}^n \frac{x_i}{n}\right) + \|x\|_2^2$$

$$G_3(x) = \frac{1}{n(n+1)} \sum_{i=1}^n i(n - i + 1) \exp(-x_i).$$

For randomly sampling 100 initial points, we consider the box region  $\mathcal{S}$  of the form

$[L, U]$ , where  $L = [-2, -2]$ , and  $U = [2, 2]$ .

**Example 12.0.7** We consider DTLZ5 [37] type SOP involving a set of 100-objective functions, is given by

$$F(x) := \{f^1(x), f^2(x), \dots, f^{100}(x)\},$$

where, for each  $i \in [100]$ ,  $f^i : \mathbb{R}^n \rightarrow \mathbb{R}^m$  is given by

$$f^i(x) = h(x) + \begin{pmatrix} 5\psi_i/2\pi \\ \lambda \cos(\phi_i)/10 \\ \lambda \sin(\phi_i)/10 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

with

$$h(x) = \begin{bmatrix} (1 + g(x_M)) \cos(\theta_1(\pi/2)) \dots \cos(\theta_{M-2}\pi/2) \cos(\theta_{M-1}\pi/2) \\ (1 + g(x_M)) \cos(\theta_1(\pi/2)) \dots \cos(\theta_{M-2}\pi/2) \sin(\theta_{M-1}\pi/2) \\ (1 + g(x_M)) \cos(\theta_1\pi/2), \dots, \sin(\theta_{M-2}\pi/2) \\ \vdots \\ (1 + g(x_M)) \sin(\theta_1\pi/2) \end{bmatrix},$$

and

$$\begin{aligned} \theta_i &= \frac{1}{2(1 + g(x_M))} (1 + g(x_M)x_i), \text{ for } i = 2, 3, \dots, (M - 1), \\ g(x_M) &= \sum_{x_i \in x_M} (x_i - 0.5)^2, \\ 0 \leq x_i &\leq 1, \text{ for } i = 1, 2, \dots, n, \end{aligned}$$

Last  $k = n - M + 1$  variables are represented as  $x_M$  and the set  $\{(\phi_i, \psi_i) : i \in [100]\}$  is an enumeration of the set  $\{\frac{\pi}{5}(j - 1) : j \in [10]\} \times \{\frac{\pi}{5}(\ell - 1) : \ell \in [10]\}$  and for randomly sampling 100 initial points, we consider the box region  $\mathcal{S}$  of the form  $[L, U]$ , where  $L = [0, 0, \dots, 0]$ ,  $U = [1, 1, \dots, 1]$ . We consider three different version of this problem where  $(n, m) = (3, 3), (5, 3), (7, 5)$ .

**Example 12.0.8** We consider DGO1 [44] type SOP involving a set of 100-objective

functions, given by

$$F(x) = \{f^1(x), f^2(x), \dots, f^{100}(x)\},$$

where for each  $i \in [100]$ ,  $f^i : \mathbb{R} \rightarrow \mathbb{R}^2$  is given by

$$f^i(x) = g(x) + \begin{pmatrix} \sin(2\pi i/100 + \cos(2\pi i/100)) \\ \cos(2\pi i/100 + \sin(2\pi i/100)) \end{pmatrix}$$

with

$$g(x) = \begin{pmatrix} \sin(x) \\ \sin(x + 0.7) \end{pmatrix}.$$

For randomly sampling 100 initial points, we consider the box region  $\mathcal{S}$  of the form  $[L, U]$ , where  $L = [-10, -10]$ ,  $U = [13, 13]$ .

**Example 12.0.9** We consider DGO2 [44] type SOP involving a set of 100 objective functions, given by

$$F(x) = \{f^1(x), f^2(x), \dots, f^{100}(x)\},$$

where, for each  $i \in [100]$ ,  $f^i : \mathbb{R} \rightarrow \mathbb{R}^2$ , is given by

$$f^i(x) = g(x) + \begin{pmatrix} \sin(2\pi i/100 + \cos(2\pi i/100)) \\ \cos(2\pi i/100 + \sin(4\pi i/100)) \end{pmatrix}$$

with

$$g(x) = \begin{pmatrix} x^2 \\ 9 - \sqrt{81 - x^2} \end{pmatrix}$$

For randomly sampling 100 initial points, we consider the box region  $\mathcal{S}$  of the form  $[L, U]$ , where  $L = [-9, -9]$ , and  $U = [9, 9]$ .

**Example 12.0.10** We consider Hil type [87] SOP involving a set of 100 objective functions, given by

$$F(x) := \{f^1(x), f^2(x), \dots, f^{100}(x)\},$$

where for each  $i \in [100]$ ,  $f^i : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  is given by

$$f^i(x) = g(x) + \begin{pmatrix} 10((9 + \exp(\sin(4\pi i/100)) - \sin(4\pi i/100) + 2(\cos(8\pi i/100))^2)/128) \cos(2\pi i/100) \\ 10((9 + \exp(\sin(4\pi i/100)) - \sin(4\pi i/100) + 2(\cos(8\pi i/100))^2)/128) \sin(2\pi i/100) \end{pmatrix}.$$

with

$$g(x) = \begin{pmatrix} \cos((2\pi/360)[45 + 40 \sin(2\pi x_1) + 25 \sin(2\pi x_2)](1 + 0.5 \cos(2\pi x_1))) \\ \sin((2\pi/360)[45 + 40 \sin(2\pi x_1) + 25 \sin(2\pi x_2)](1 + 0.5 \cos(2\pi x_1))). \end{pmatrix}$$

For randomly sampling 100 initial points, we consider the box region  $\mathcal{S}$  of the form  $[L, U]$ , where  $L = [0, 0]$ , and  $U = [5, 5]$ .

**Example 12.0.11** We consider JOS1a [98] type SOP involving 100 objective functions, given by

$$F(x) = \{f^1(x), f^2(x), \dots, f^{100}(x)\},$$

where for each  $i \in [100]$ ,  $f^i : \mathbb{R}^{50} \rightarrow \mathbb{R}^2$  is given by

$$f^i(x) = g(x) + \begin{pmatrix} 0.1 \cos(2\pi i/100) \\ 50 \sin(2\pi i/100) \end{pmatrix}$$

with

$$g(x) = \begin{pmatrix} \frac{1}{n} \sum_{i=1}^n x_i^2 \\ \frac{1}{n} \sum_{i=1}^n (x_i - 2)^2 \end{pmatrix}.$$

For randomly sampling 100 initial points, we consider the box region  $\mathcal{S}$  of the form  $[L, U]$ , where  $L = [-2, -2, \dots, -2]$ , and  $U = [2, 2, \dots, 2]$ .

**Example 12.0.12** We consider Rosenbrock [176] type SOP involving a set of 100-objective functions, given by

$$F(x) = \{f^1(x), f^2(x), \dots, f^{100}(x)\},$$

where, for each  $i \in [100]$ ,  $f^i : \mathbb{R}^4 \rightarrow \mathbb{R}^3$  is given by

$$f^i(x) = \begin{pmatrix} 100(x_2 - x_1^2)^2 + (x_2 - 1)^2 + (r^2(\cos \phi_i \cos(\psi_i) \sin(\psi_i))) \\ 100(x_3 - x_2^2)^2 + (x_3 - 1)^2 + (r^2(\cos \phi_i \sin(\psi_i) \sin(\psi_i))) \\ 100(x_4 - x_3^2)^2 + (x_4 - 1)^2 + (r^2(\cos \phi_i \sin(\psi_i) \cos^2(\psi_i))) \end{pmatrix}.$$

For randomly sampling 100 initial points, we consider the box region  $\mathcal{S}$  of the form

$[L, U]$ , where  $L = [-2, -2, \dots, -2]$ ,  $U = [2, 2, \dots, 2]$ . We set  $r = 16$  and the set  $\{(\phi_i, \psi_i) : i \in [100]\}$  is an enumeration of the set  $\{\frac{\pi}{5}(j-1) : j \in [10]\} \times \{\frac{\pi}{5}(k-1) : k \in [10]\}$ .

**Example 12.0.13** We consider Brown and Dennis [147] type SOP involving a set of 100 objective functions, given by

$$F(x) = \{f^1(x), f^2(x), \dots, f^{100}(x)\},$$

where for each  $i \in [100]$ ,  $f^i : \mathbb{R}^4 \rightarrow \mathbb{R}^5$  is given by

$$f^i(x) = \begin{pmatrix} (x_1 + \frac{1}{5}x_2 - \exp^{\frac{1}{5}})^2 + (x_3 + x_4 \sin(\frac{1}{5}) - \cos(\frac{1}{5}))^2 + \cos(\phi_i) \sin(\psi_i) \\ (x_1 + \frac{2}{5}x_2 - \exp^{\frac{2}{5}})^2 + (x_3 + x_4 \sin(\frac{2}{5}) - \cos(\frac{2}{5}))^2 + \sin(\phi_i) \sin(\psi_i) \\ (x_1 + \frac{3}{5}x_3 - \exp(\frac{3}{5}))^2 + (x_3 + x_4 \sin(\frac{3}{5}) - \cos(\frac{3}{5}))^2 + (\cos(\psi_i) + \log(\tan(\frac{\psi_i}{2}))) + 0.5\phi_i \end{pmatrix}.$$

For randomly sampling 100 initial points, we consider the box region  $\mathcal{S}$  of the form  $[L, U]$ , where  $L = [-25, -5, -5, -1]$ , and  $U = [25, 5, 5, 1]$ . The set  $\{(\phi_i, \psi_i) : i \in [100]\}$  is an enumeration of the set  $\{\frac{2\pi}{5}(j-1) : j \in [10]\} \times \{0.01 + \frac{0.98}{10}(k-1) : k \in [10]\}$ .

**Example 12.0.14** We consider Trigonometric [147] type SOP involving a set of 100 objective functions, given by

$$F(x) = \{f^1(x), f^2(x), \dots, f^{100}(x)\},$$

where, for each  $i \in [100]$ ,  $f^i : \mathbb{R}^4 \rightarrow \mathbb{R}^4$  is given by

$$f^i(x) = \begin{pmatrix} (1 - \cos x_1 + (1 - \cos x_1) - \sin x_1)^2 + \cos(\phi_i) \sin(\psi_i) \\ (2 - \cos(x_1 + x_2) + 2(1 - \cos x_2) - \sin x_2)^2 + \sin(\phi_i) \sin(\psi_i) \\ (3 - \cos(x_1 + x_2 + x_3) + 3(1 - \cos x_3) - \sin x_3)^2 + (\cos(\psi) + \log(\tan(\frac{\psi_i}{2}))) + 0.2\phi_i \\ (4 - \cos(x_1 + x_2 + x_3 + x_4) + 4(1 - \cos x_4) - \sin x_4) \end{pmatrix},$$

For randomly sampling 100 initial points, we consider the box region  $\mathcal{S}$  of the form  $[L, U]$ , where  $L = [-1, -1, \dots, -1]$ , and  $U = [1, 1, \dots, 1]$ . The set  $\{(\phi_i, \psi_i) : i \in [100]\}$  is an enumeration of the set  $\{\frac{2\pi}{5}(j-1) : j \in [10]\} \times \{0.01 + \frac{0.98}{10}(k-1) : k \in [10]\}$ .

**Example 12.0.15** We consider Das and Dennis [36] type involving a set of 100 objective functions, given by

$$F(x) = \{f^1(x), f^2(x), \dots, f^{100}(x)\},$$

where, for each  $i \in [100]$ ,  $f^i : \mathbb{R}^5 \rightarrow \mathbb{R}^2$ , is given by

$$f^i(x) = \begin{pmatrix} (x_1^2 + x_2^2 + x_3^2 + x_4^2 + x_5^2 + (\sin(\frac{2i\pi}{100}) + \cos(\frac{2i\pi}{100}))) \\ (3x_1 + 2x_2 - \frac{x_3}{3} + 0.01(x_4 - x_5)^3 + (\sin(\frac{2i\pi}{100}) + \cos(\frac{2i\pi}{100}))) \end{pmatrix},$$

*For randomly sampling 100 initial points, we consider the box region  $\mathcal{S}$  of the form  $[L, U]$ , where  $L = [-20, -20, \dots, -20]$ , and  $U = [20, 20, \dots, 20]$ .*

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# LIST OF PUBLICATIONS

1. Suprova Ghosh, Debdas Ghosh, and Anshika. Normal and tangent cones for set of intervals and their application in optimization with functions of interval variables. *Soft Computing*, 27 (2023) 10737–10758.
2. Suprova Ghosh, Debdas Ghosh, Adrian Petruşel and Xiaopeng Zhao. Generalized Hukuhara Weak subdifferential and its application on identifying optimality conditions for nonsmooth interval-valued functions. *Journal of Nonlinear and Variational Analysis*, 8 (2024) 333–368.
3. Debdas Ghosh and Suprova Ghosh. Sufficient optimality conditions and Duality for a nonsmooth interval-valued optimization problem with Generalized Convexity via  $gH$ -Clarke subgradients. In *Continuous Optimization and Variational Inequalities*. Chapman and Hall/CRC, 2022, pp. 219–242.
4. Debdas Ghosh, Suprova Ghosh, Christiane Tammer, Jen-Chih Yao, and Xiaopeng Zhao. Trust-region method for set optimization problems with set-valued mapping of finitely many vector-valued functions, 2024. (Communicated)
5. Debdas Ghosh, Suprova Ghosh, and Christiane Tammer. Nonmonote trust-region method for set optimization problems with set-valued mapping of finitely many vector-valued functions, 2024. (Communicated)
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