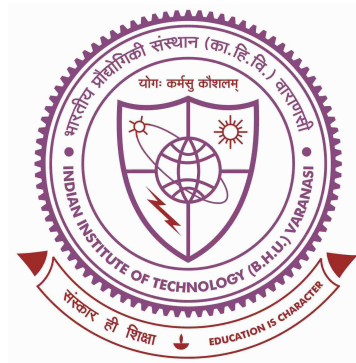


Accelerated Optimization and Control Using Predefined-Time Convergent Dynamical Systems



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by

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